# $11^{\text {th }}$ International Workshop on Higher-Order Rewriting (HOR 2023) 

Carsten Fuhs (Editor)

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## Editor's Preface

This volume contains the informal proceedings of the $11^{\text {th }}$ International Workshop on HigherOrder Rewriting, to be held on $4^{\text {th }}$ July 2023 in Rome, Italy:
https://hor2023.github.io/
HOR is a forum to present work concerning all aspects of higher-order rewriting. The aim is to provide an informal and friendly setting to discuss recent work and work in progress. The following is a non-exhaustive list of topics for the workshop:

- Applications: proof checking, theorem proving, generic programming, declarative programming, program transformation, automated termination/confluence/equivalence analysis tools.
- Foundations: pattern matching, unification, strategies, narrowing, termination, syntactic properties, type theory, complexity of derivations.
- Frameworks: term rewriting, conditional rewriting, graph rewriting, net rewriting, comparisons of different frameworks.
- Implementation: explicit substitution, rewriting tools, compilation techniques.
- Semantics: semantics of higher-order rewriting, categorical rewriting, higher-order abstract syntax, games and rewriting.

The International Workshop on Higher-Order Rewriting has played an important role in the last two decades of developments in the field. Starting in 2002, the workshop took place loosely every other year:

HOR 2002 (Copenhagen, Denmark), affiliated with FLoC 2002
HOR 2004 (Aachen, Germany), affiliated with RDP 2004
HOR 2006 (Seattle, USA), affiliated with FLoC 2006
HOR 2007 (Paris, France), affiliated with RDP 2007
HOR 2010 (Edinburgh, UK), affiliated with FLoC 2010
HOR 2012 (Nagoya, Japan), affiliated with RTA 2012
HOR 2014 (Vienna, Austria), affiliated with FLoC 2014
HOR 2016 (Porto, Portugal), affiliated with FSCD 2016
HOR 2018 (Oxford, UK), affiliated with FLoC 2018
HOR 2019 (Dortmund, Germany), affiliated with FSCD 2019
Information about previous editions can be found at https://hor.irif.fr/.
HOR 2023 is affiliated with the $8^{\text {th }}$ International Conference on Formal Structures for Computation and Deduction (FSCD 2023) and the 29 ${ }^{\text {th }}$ International Conference on Automated Deduction (CADE-29).

The $11^{\text {th }}$ Workshop on Higher-Order Rewriting features six regular extended abstracts, contained in this volume, and an invited talk by Pablo Barenbaum (Universidad de Buenos Aires, Argentina) on Quantitative Types for Useful Reduction.

I would like to thank everyone who helped to prepare and run the workshop: the participants, the programme committee, the steering committee, and the local organisers.

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# A Deeper Study of $\lambda!$-Calculus Simulations 

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Abstract<br>In this paper we study properties of the encodings of CBN and CBV into a CBPV like language

## 1 Introduction

Bang Calculus. P.B. Levy introduced Call-by-Push-Value (CBPV) 13 as a subsuming language, so that different evaluation strategies of the $\lambda$-calculus can be captured in a uniform framework by the simple use of two primitives: thunk (to pause a computation) and force (to resume a computation). This mechanism is powerful enough to encode, in particular, Call-by-Name (CBN) and Call-by-Value [14 (CBV). The original CBPV has been introduced in a simply typed framework, but the underlying (untyped) syntax and operational semantics -the ones we are interested in here- already provide a powerful untyped subsuming mechanism. Despite that, CBN and CBV have always been studied notably by developing different techniques for one and the other. Some rare exceptions are [5, 8, 12, 3], where some particular property for CBN/CBV (e.g. quantitative typing, factorization, tight typing, inhabitation) is derived from the corresponding property for a language that is a restriction of CBPV, via a suitable CBN/CBV encoding. Such a language can be the bang calculus [7, 10, 11] (in turn inspired by Ehrhard [6], combining ideas from Levy's CBPV 13$]$ and Girard's linear logic [9), or its variant the $\lambda$ !-calculus [5, 12] where reduction rules act at a distance.

Normal Form, Simulation and Reverse Simulation. In this work, we are interested in the preservation of the reduction relation by the encoding. On one hand and from a static point of view, one may consider the preservation of normal forms: $t$ is a normal form if and only if $t^{e}$ is a normal form, where $t^{e}$ is the $e$-encoding of $t$. On the second hand and from a more dynamical point of view, two properties can naturally be considered. Simulation: reduction steps are transported into the subsuming paradigm (i.e. if $t \rightarrow u$ in the subsumed language then $t^{e} \rightarrow u^{e}$ in the subsuming language). Reverse simulation: reduction steps are recovered from the subsuming paradigm (i.e. if $t^{e} \rightarrow u^{e}$ in the subsuming language then $t \rightarrow u$ in the subsumed language).

Some of these properties have been studied for CBPV [13], bang calculus [10] and $\lambda!$-calculus 5 but a full analysis is still missing. In this work, we look into the normal form preservation, simulation and reverse simulation for the $\lambda!$-calculus. In particular, taking into account distance is not a trivial matter in that it requires modifications of the call-by-value encoding.

## 2 The $\lambda!$-Calculus

We now briefly introduce the $\lambda!$-calculus [5]. Given a countably infinite set $\mathcal{X}$ of variables $x, y, z, \ldots$, the set $\Lambda_{!}$of terms is given by the following inductive definition:

$$
\text { (Terms) } \quad t, u \quad::=\quad x \in \mathcal{X}|\lambda x . t| t u|t[x \backslash u]|!t \mid \operatorname{der}(t)
$$

$$
\begin{aligned}
x^{\mathrm{cbn}} & =x & x^{\mathrm{cbv}} & =!x \\
(\lambda x . t)^{\mathrm{cbn}} & =\lambda x \cdot t^{\mathrm{cbn}} & (\lambda x \cdot t)^{\mathrm{cbv}} & =!\lambda x \cdot t^{\mathrm{cbv}} \\
(t u)^{\mathrm{cbn}} & =t^{\mathrm{cbn}}!u^{\mathrm{cbn}} & (t u)^{\mathrm{cbv}} & = \begin{cases}\mathrm{L}\langle s\rangle u^{\mathrm{cbv}} & \text { if } t^{\mathrm{cbv}}=\mathrm{L}\langle!s\rangle \\
\operatorname{der}\left(t^{\mathrm{cbv}}\right) u^{\mathrm{cbv}} & \text { otherwise }\end{cases} \\
(t[x \backslash u])^{\mathrm{cbn}} & =t^{\mathrm{cbn}}\left[x \backslash!u^{\mathrm{cbn}}\right] & (t[x \backslash u])^{\mathrm{cbv}} & =t^{\mathrm{cbv}}\left[x \backslash u^{\mathrm{cbv}}\right]
\end{aligned}
$$

Figure 1: CbN and CbV Embeddings for $\lambda!$-Calculus 5

The set $\Lambda_{!}$includes $\lambda$-terms (variables $x$, abstractions $\lambda x$.t and applications $t u$ ) as well as three new constructors: a closure $t[x \backslash u]$ representing a pending explicit substitution $[x \backslash u]$ on a term $t$, a bang ! to freeze the execution of $t$, and a dereliction $\operatorname{der}(t)$ to fire again the frozen term $t$. The usual notion of $\alpha$-conversion [4] is extended to the whole set $\Lambda_{!}$, and terms are identified up to $\alpha$-conversion. We denote by $t\{x:=v\}$ the usual (capture avoiding) meta-level substitution of the term $u$ for all free occurrences of the variable $x$ in the term $t$.

The sets of list contexts L, surface contexts S and full contexts F, which can be seen as terms containing exactly one hole $\diamond$, are inductively defined as follows:

$$
\begin{array}{rccc|}
\text { (List) } & \mathrm{L} & ::= & \diamond \mid \mathrm{L}[x \backslash t] \\
\text { (Surface) } & \mathrm{S} & ::= & \diamond|\lambda x . \mathrm{S}| \mathrm{S} t|t \mathrm{~S}| \mathrm{S}[x \backslash t]|t[x \backslash \mathrm{~S}]| \operatorname{der}(\mathrm{S}) \\
(\text { Full) } & \mathrm{F} & ::= & \diamond|\lambda x . \mathrm{F}| \mathrm{F} t|t \mathrm{~F}| \mathrm{F}[x \backslash t]|t[x \backslash \mathrm{~F}]| \operatorname{der}(\mathrm{F}) \mid!\mathrm{F}
\end{array}
$$

The hole can occur everywhere in F , while in S it cannot occur under a !. We write $\mathrm{L}\langle t\rangle$ for the term obtained by replacing the hole in L with the term $t$ and similarly for S and F .

The following three rewriting rules are the base components of our reduction relations:

$$
\mathrm{L}\langle\lambda x . t\rangle u \quad \mapsto_{\mathrm{dB}} \quad \mathrm{~L}\langle t[x \backslash u]\rangle \quad t[x \backslash \mathrm{~L}\langle!u\rangle] \quad \mapsto_{\mathrm{s}!} \quad \mathrm{L}\langle t\{x:=u\}\rangle \quad \operatorname{der}(\mathrm{L}\langle!t\rangle) \quad \mapsto_{\mathrm{d}}!\quad \mathrm{L}\langle t\rangle
$$

Rule dB (resp. s!) is assumed to be capture free, so no free variable of $u$ (resp. $t$ ) is captured by the context $L$. The rule $d B$ fires a standard $\beta$-redex and generates an explicit substitution. The rule s! fires an explicit substitution provided that its argument is a bang. The rule d! defrosts a frozen term. In all of these rewrite rules, the reduction acts at a distance [1]: the main constructors involved in the rule can be separated by a finite - possibly empty- list L of explicit substitutions. This mechanism unblocks redexes that otherwise would be stuck, e.g. $(\lambda x . x)[y \backslash w]!z \mapsto_{\mathrm{dB}} x[x \backslash!z][y \backslash w]$ fires a $\beta$-redex by taking $\mathrm{L}=\diamond[y \backslash w]$ as the list context in between the function $\lambda x . x$ and the argument $!z$.

The surface reduction relation $\rightarrow_{\mathrm{s}}$ is the surface closure of any of the three rewrite rules dB , s ! and d!, i.e. $\rightarrow_{\mathrm{s}}$ only fires redexes in surface contexts, and not under bang. Similarly, the full reduction relation $\rightarrow_{F}$ is the full closure of any of the rewrite rules, so that $\rightarrow_{F}$ reduces under full contexts and thus the bang loses its freezing behavior. For example,

$$
(\lambda x .!\operatorname{der}(!x))!y \quad \rightarrow_{\mathrm{S}} \quad(!\operatorname{der}(!x))[x \backslash!y] \quad \rightarrow_{\mathrm{S}} \quad!\operatorname{der}(!y) \quad \rightarrow_{\mathrm{F}} \quad!y
$$

Note that the first two steps are also $\rightarrow_{\mathrm{F}}$-steps, while the last step is not an $\rightarrow_{\mathrm{s}}$-step. More generally, we have $\rightarrow_{\mathrm{S}} \subseteq \rightarrow_{\mathrm{F}}$. Moreover, we denote by $\rightarrow_{\mathrm{S}}$ (resp. $\rightarrow_{\mathrm{F}}$ ) the reflexive and transitive closure of $\rightarrow_{\mathrm{S}}\left(\right.$ resp. $\left.\rightarrow_{\mathrm{F}}\right)$.

## 3 Call-by-Name - $\lambda_{n}$

We now briefly introduce the (call-by-name) $\lambda_{n}$-calculus. Given a countably infinite set $\mathcal{X}$ of variables $x, y, z, \ldots$, the set $\Lambda_{\mathrm{n}}$ of terms is given by the following inductive definition:

$$
\text { (Terms) } \quad t, u \quad::=\quad x \in \mathcal{X}|\lambda x . t| t u \mid t[x \backslash u]
$$

Terms are identified up the the usual notion of $\alpha$-conversion 44 and we denote by $t\{x:=v\}$ the expected (capture avoiding) meta-level substitution. The sets of list contexts L, surface contexts N and full contexts C , are inductively defined as follows:

$$
\begin{array}{rccc}
\text { (List) } & \mathrm{L} & ::= & \diamond \mid \mathrm{L}[x \backslash t] \\
\text { (Surface) } & \mathrm{N} & ::= & \diamond|\lambda x . \mathrm{N}| \mathrm{N} t \mid \mathrm{N}[x \backslash t] \\
\text { (Full) } & \mathrm{C} & ::= & \diamond|\lambda x . \mathrm{C}| \mathrm{C} t|t \mathrm{C}| \mathrm{C}[x \backslash t] \mid t[x \backslash \mathrm{C}]
\end{array}
$$

The hole can occur everywhere in $C$, while in $N$ it cannot occur in the argument of an application nor an explicit substitution.

The following rewriting rules are the base components of our reduction relations:

$$
\mathrm{L}\langle\lambda x . t\rangle u \quad \mapsto_{\mathrm{dB}} \quad \mathrm{~L}\langle t[x \backslash u]\rangle \quad t[x \backslash u] \quad \mapsto_{\mathrm{s}} \quad t\{x:=u\}
$$

The surface reduction relation $\rightarrow_{N}$ (resp. full reduction relation $\rightarrow_{C}$ ) is defined as the surface closure $N$ (resp. full closure $C$ ) of the rules dB and s presented above. Moreover, we denote by $\rightarrow_{\mathrm{N}}$ (resp. $\rightarrow_{\mathrm{C}}$ ) the reflexive transitive closure of the surface reduction $\rightarrow_{\mathrm{N}}$ (resp. full reduction $\rightarrow_{\mathrm{C}}$ ). Finally, a term $t \in \Lambda_{\mathrm{n}}$ is said in to be a surface (resp. full) normal form if there is no $u$ such that $t \rightarrow_{\mathrm{N}} u\left(\right.$ resp. $\left.t \rightarrow_{\mathrm{C}} u\right)$.

The embedding .cbn presented in (Fig. 1) has been shown 5 to preserve surface normal forms. However, this property can be strengthen to also include full normal forms:

Theorem 3.1 (Normal Forms Preservation). Let $t \in \Lambda_{\mathrm{n}}$, then $t$ is a surface (resp. full) normal form if and only if $t^{\mathrm{cbn}}$ is a surface (resp. full) normal form.

Rather than just looking at static properties, we are actually interested in dynamic ones. In particular, surface reduction is well transported into the bang calculus (simulation property in [5]). Interestingly, we show that it also holds for the full reduction. Moreover, we show that reverse simulation is also verified for both surface and full reductions.

Theorem 3.2 (Surface/Full Simulation and Reverse Simulation). Let $t, u \in \Lambda_{\mathrm{n}}$, then:

- $t \rightarrow_{\mathrm{N}} u\left(\right.$ resp. $\left.t \rightarrow_{\mathrm{N}} u\right)$ if and only if $t^{\mathrm{cbn}} \rightarrow_{\mathrm{s}} u^{\mathrm{cbn}}\left(\right.$ resp. $\left.t^{\mathrm{cbn}} \rightarrow_{\mathrm{s}} u^{\mathrm{cbn}}\right)$.
- $t \rightarrow_{\mathrm{C}} u\left(\right.$ resp. $\left.t \rightarrow_{\mathrm{C}} u\right)$ if and only if $t^{\mathrm{cbn}} \rightarrow_{\mathrm{F}} u^{\mathrm{cbn}}\left(\right.$ resp. $t^{\mathrm{cbn}} \rightarrow_{\mathrm{F}} u^{\mathrm{cbn}}$ ).

Moreover, the number of dB (resp. s) steps exactly matches the number of dB (resp. s!) steps.

## 4 Call-by-Value - $\lambda_{\text {vsub }}$

We now briefly introduce the (distant call-by-value) $\lambda_{\mathrm{vsub}}$-calculus 2]. The set $\Lambda_{\mathrm{v}}$ of terms is given by the following inductive definitions:

$$
\begin{array}{lrll}
\text { (Terms) } & t, u & ::= & v|t u| t[x \backslash u] \\
\text { (Values) } & v & ::= & x \in \mathcal{X} \mid \lambda x . t
\end{array}
$$

| In $\Lambda_{\mathrm{n}}:$ | $(\lambda x \cdot((\lambda y \cdot y) z)) z$ | $\not_{\mathrm{v}}$ | $(\lambda x \cdot(y[y \backslash z])) z$ |
| :---: | :---: | :---: | :---: |
|  | $\downarrow \cdot \mathrm{cbv}$ |  | $\downarrow^{\mathrm{cbv}}$ |
| In $\Lambda_{!}:$ | $(\lambda x \cdot((\lambda y!!y)(!z)))(!z)$ | $\rightarrow_{\mathrm{s}}$ | $(\lambda x \cdot((!y)[y \backslash!z]))(!z)$ |

Figure 2: A Counterexample of the CbV Reverse Simulation Property

$$
\begin{array}{rll}
x^{\mathrm{CBv}} & =!x \\
(\lambda x . t)^{\mathrm{CBv}} & =!\lambda x .!t^{\mathrm{CBV}} \\
(t u)^{\mathrm{CBv}} & = \begin{cases}\operatorname{der}\left(\mathrm{L}\langle s\rangle u^{\mathrm{CBV}}\right) & \text { if } t^{\mathrm{CBV}}=\mathrm{L}\langle!s\rangle \\
\operatorname{der}\left(\operatorname{der}\left(t^{\mathrm{CBv}}\right) u^{\mathrm{CBV}}\right) & \text { otherwise } \\
(t[x \backslash u])^{\mathrm{CBv}} & =t^{\mathrm{CBV}}\left[x \backslash u^{\mathrm{CBV}}\right]\end{cases}
\end{array}
$$

Figure 3: A New Call-by-Value Embedding for Bang-calculus

Again, we consider the set of terms up to the usual $\alpha$-conversion 4 and we denote by $t\{x:=v\}$ the expected (capture avoiding) meta-level substitution. The sets of list contexts L, surface contexts V and full contexts C , are inductively defined as follows:

$$
\begin{array}{rccc}
\text { (List) } & \mathrm{L} & ::=\diamond \mid \mathrm{L}[x \backslash t] \\
\text { (Surface) } & \mathrm{V} & ::=\diamond|\mathrm{V} t| t \mathrm{~V}|\mathrm{~V}[x \backslash t]| t[x \backslash \mathrm{~V}] \\
\text { (Full) } & \mathrm{C} & ::= & \diamond|\lambda x . \mathrm{C}| \mathrm{C} t|t \mathrm{C}| \mathrm{C}[x \backslash t] \mid t[x \backslash \mathrm{C}]
\end{array}
$$

In particular, the hole can occur everywhere in C , while in V it cannot occur under an abstraction. The following rewriting rules are the base components of our reduction relations.

$$
\mathrm{L}\langle\lambda x . t\rangle u \quad \mapsto_{\mathrm{dB}} \quad \mathrm{~L}\langle t[x \backslash u]\rangle \quad t[x \backslash \mathrm{~L}\langle v\rangle] \quad \mapsto_{\mathrm{sv}} \quad \mathrm{~L}\langle t\{x:=v\}\rangle
$$

In both these rules the reduction acts at a distance in order to deal with stuck redexes since this phenomenon also appear in call-by-value. The surface reduction relation $\rightarrow_{\mathrm{v}}$ (resp. full reduction relation $\rightarrow_{C}$ ) is defined as the surface closure $V$ (resp. full closure $C$ ) of the rules $d B$ and sV presented above. We denote by $\rightarrow_{\mathrm{v}}$ (resp. $\rightarrow_{\mathrm{C}}$ ) the reflexive transitive closure of the surface reduction $\rightarrow_{\mathrm{V}}$ (resp. full reduction $\rightarrow_{\mathrm{C}}$ ) and finally, a term $t \in \Lambda_{\mathrm{v}}$ is said in to be a surface (resp. full) normal form if there is no $u$ such that $t \rightarrow_{\mathrm{V}} u$ (resp. $t \rightarrow_{\mathrm{C}} u$ ).

The embedding .cbv presented in Fig. 1 preserves surface normal forms and satisfies the simulation property for the surface reduction [5]. However, reverse simulation fails for the surface reduction. A counter example can be found in Fig 2.

We introduce in Fig. 3 a new call-by-value embedding .CBv solving the issue. The main difference can be found in the abstraction case where two ! are used instead of one. The application is then adapted by placing an additional dereliction on the outside. This dereliction gets rid of the bang on the body of the abstraction once the dB redex has been fired. This restores access to the body of the previously existing abstraction, matching the phenomenon at play in distance.

This new embedding has the same good static property of preserving the surface normal forms and is additionally shown to preserve full normal forms.

Theorem 4.1 (Normal Forms Preservation). Let $t \in \Lambda_{\mathrm{v}}$, then $t$ is a surface (resp. full) normal form if and only if $t^{\mathrm{CBV}}$ is a surface (resp. full) normal form.

Moreover and as intended, this new encoding is satisfying both simulation and reverse simulation properties for both surface and full reductions:

Theorem 4.2 (Surface/Full Simulation and Reverse Simulation). Let $t, u \in \Lambda_{\text {vsub }}$, then:

- $t \rightarrow_{\mathrm{v}} u\left(\right.$ resp. $\left.t \rightarrow \rightarrow_{\mathrm{v}} u\right)$ if and only if $t^{\mathrm{CBV}} \rightarrow_{\mathrm{s}} u^{\mathrm{CBv}}$.
- $t \rightarrow_{\mathrm{C}} u$ (resp. $t \rightarrow_{\mathrm{C}} u$ ) if and only if $t^{\mathrm{CBV}} \rightarrow_{\mathrm{F}} u^{\mathrm{CBV}}$.
where the number of dB (resp. s ) steps exactly matches the number of dB (resp. $\mathrm{s}!$ ) steps.


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# A Confluence Criterion for Non Left-Linearity in a $\beta \eta$-Free Reformulation of HRSs 

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#### Abstract

We give a criterion for showing confluence of non-left linear (Pattern) Higher-order Rewrite Systems (HRSs). More precisely, our criterion concerns 2nd order signatures and allows one to show object confluence, that is, confluence when restricting to terms only with variables of order 0 . As a second contribution, we give a reformulation of HRSs in which one never needs to speak of meta-level $\beta \eta$-equality.


## 1 Introduction

When proving confluence in Nipkow's (Pattern) Higher-order Rewrite Systems (HRSs) 8], one generally has to be in one of the two following cases. If the rewrite system being considered is (1) strongly normalizing (s.n.), then by the critical pair lemma it suffices to check that critical pairs are joinable [8]. In most situations this is too strong of a requirement, but fortunately if the system is (2) left-linear then many criteria exist, such as orthogonality [9] and development-closedness [10. If however neither (1) nor (2) hold, then no known criteria allows for showing confluence. This is problematic even when non-linearity is only necessary for silly reasons, such as in the following example.
$\Sigma_{\lambda \pi^{\uparrow}}=\lambda:(\mathrm{t}: \mathrm{tm} \rightarrow \mathrm{tm}) \rightarrow \mathrm{tm}, @:(\mathrm{t}: \mathrm{tm}, \mathrm{u}: \mathrm{tm}) \rightarrow \mathrm{tm}, \quad \uparrow:(\mathrm{n}:|\mathrm{lv}|, \mathrm{m}: \mid \mathrm{lv}, \mathrm{t}: \mathrm{tm}) \rightarrow \mathrm{tm}$, $\pi:(\mathrm{n}: \mid \mathrm{vl}, \mathrm{a}: \mathrm{tm}, \mathrm{b}: \mathrm{tm} \rightarrow \mathrm{tm}) \rightarrow \mathrm{tm}, \quad 0:|\mathrm{v}|, \quad \mathrm{S}:(\mathrm{n}:|\mathrm{v}|) \rightarrow|\mathrm{v}|$
$\mathcal{R}_{\lambda \pi^{\uparrow}}=\uparrow_{\mathrm{n}}^{\mathrm{m}}\left(\pi_{\mathrm{n}}(\mathrm{A}, x . \mathrm{B}(x))\right) \longmapsto \pi_{\mathrm{m}}\left(\uparrow_{\mathrm{n}}^{\mathrm{m}}(\mathrm{A}), x . \uparrow_{\mathrm{n}}^{\mathrm{m}}(\mathrm{B}(x))\right) \quad \uparrow_{\mathrm{n}}^{\mathrm{n}}(\mathrm{t}) \longmapsto \mathrm{t}$

$$
\lambda(x . \mathrm{t}(x)) @ \mathrm{u} \longmapsto \mathrm{t}(\mathrm{u}) \quad \uparrow_{\mathrm{m}}^{\mathrm{p}}\left(\uparrow_{\mathrm{n}}^{\mathrm{m}}(\mathrm{t})\right) \longmapsto \uparrow_{\mathrm{n}}^{\mathrm{p}}(\mathrm{t})
$$

Example 1. Consider the signature (where tm, IvI are sorts) and the rewrite system given above, containing an excerpt of the rules used when defining a cumulative Tarski-style universe - similar ones can be found in 3. Because of the beta rule, the rewrite system is not s.n. and because of the other rules the system is also non left-linear. Non-linearity is only used to obtain a finite signature, a pre-requisite for some applications.

Actually, there is no hope of showing confluence for $\mathcal{R}_{\lambda \pi^{\uparrow}}$, given that it is possible to simulate the rewrite system $\mathcal{R}_{k}=\{\lambda(x . \mathrm{t}(x)) @ \mathrm{u} \longmapsto \mathrm{t}(\mathrm{u}), f(\mathrm{t}, \mathrm{t}) \longmapsto a\}$ shown by Klop to be not confluent [7]. Indeed, by taking variables $x: \mathrm{tm} \rightarrow \mathrm{Ivl}, y: \mathrm{tm}$ we can translate $\llbracket f(t, u) \rrbracket:=\uparrow_{x(\llbracket t \rrbracket)}^{x(\llbracket u)}(y)$ and $\llbracket a \rrbracket:=y$, and then show that $t \longrightarrow u$ implies $\llbracket t \rrbracket \longrightarrow \llbracket u \rrbracket$ and $\llbracket t \rrbracket \longrightarrow u$ implies $t \longrightarrow u^{\prime}$ for some $u^{\prime}$ with $\llbracket u^{\prime} \rrbracket=u$. Using these two facts it is easy to see that the confluence of $\mathcal{R}_{\lambda \pi^{\uparrow}}$ implies that of $\mathcal{R}_{k}$.

This counterexample however makes essential use of the fact that we have access to a variable $x: \operatorname{tm} \rightarrow \mathrm{Iv}$, allowing us to perform a beta step inside a non-linear position of the lhs in $\uparrow_{n}^{n}(t) \longmapsto t$. However, in most applications one is only interested in terms containing 0 -order variables, and higher-order variables are only used as metavariables to define the rewrite rules. If we instead restrict our attention to confluence over terms containing only variables of order 0 (a property we will call object confluence), can we prove that $\mathcal{R}_{\lambda \pi \uparrow} \uparrow$ satisfies this property?

In this article, we propose a criterion that allows us to do that. More precisely, given two rewrite systems $\mathcal{R}_{l}$ and $\mathcal{R}_{n l}$ over a signature of order at most 2 such that (1) both are
object confluent, (2) $\mathcal{R}_{l}$ is linear, (3) there are no critical pairs between them and (4) the sorts of non-linear lhs variables of $\mathcal{R}_{n l}$ are inaccessible from the sorts of the rules in $\mathcal{R}_{l}$, our criterion allows one to conclude object confluence of their union. The proof is a simple adaptation of the proof of confluence by orthogonality, by using condition (4) to show that a $\mathcal{R}_{l}$ step cannot destroy a $\mathcal{R}_{n l}$ redex. As shown in the end of the article, our criterion proves the object confluence of Example 1 .

As a second contribution, we give a reformulation of Nipkow's HRSs in which one never needs to talk about $\beta \eta$-equivalence. This is achieved by adopting a canonical forms only presentation of the simply-typed $\lambda$-calculus, and replacing regular substitution by hereditary substitution [6]. This avoids the technicalities of switching $\beta \eta$ representatives and allows for a presentation of higher-order rewriting that we believe can be clearer.
Related work The problem of higher-order confluence with non-left linear rules has been studied by [2] and [3] in the setting of rewriting union $\beta$. The notion of confinement introduced in [2] was an essential inspiration for us. We omit a detailed discussion because of size constraints, but remark that our criterion's proof is much shorter and less technical.

## 2 Higher-order rewriting

We start by introducing our reformulation of Nipkow's (Pattern) Higher-order Rewriting Systems (HRSs). We suppose we are given three infinite and disjoint sets of variables $\mathcal{V}$, refered to by $x, y, z$ or by letters in typewriter font such as a, $\mathrm{b}, \mathrm{t}$, (syntactic) constructors $\mathcal{C}$, refered to by $c, d, f, g$, and sorts $\mathcal{S}$, refered to by $s$. A head $h$ is either a constructor $c$ or a variable $x$. We define arities, scopes and signatures by the grammars

$$
\text { Arity } \ni \sigma, \tau::=\delta \rightarrow s \quad \text { Scope } \ni \gamma, \delta::=\cdot \mid \gamma, x: \tau \quad \text { Sig } \ni \Sigma::=\cdot \mid \Sigma, c: \tau
$$

and abbreviate $\cdot \rightarrow s$ as simply $s$. We write $\vec{x}_{\gamma}$ for the sequence of variables in $\gamma$, and $\gamma . \delta$ for concatenation. A subscope $\gamma^{\prime}$ of $\gamma$ is a subsequence of $\gamma$, written $\gamma^{\prime} \sqsubseteq \gamma$.

In other works, one usually calls $\gamma$ a context and $\tau$ a simple type. We however prefer to insist here on a different point of view, in which $\tau$ is seen as a higher-order generalization of the regular notion of arity.

Given a fixed signature $\Sigma$, terms and spines are mutually defined by the following inference rules. From the perspective of the $\lambda$-calculus, our terms can be seen as the simply-typed $\lambda$-terms of some base type, and in $\beta$-normal $\eta$-long form (or canonical form). However, our definition allows us to capture directly the terms of interest, and unlike 8] we never need to speak about the non canonical forms, which play only a bureaucratic role. The definition also clarifies the fact that higher-order rewriting is not (or at least does not need to be seen as) a form of rewriting modulo, but instead rewriting in which one adopts a different notion of substitution (as we will see next).

In the following, when convenient we abbreviate $h(\varepsilon)$ as $h$. We write $e \in \operatorname{Expr} \gamma$ when either $e \in \operatorname{Tm} \gamma s$ or $e \in \operatorname{Sp} \gamma \delta$, and we call $e$ an expression. Finally, given a spine $\mathbf{t} \in \operatorname{Sp} \gamma \delta$ and a variable $x: \gamma_{x} \rightarrow s_{x} \in \delta$, we write $\mathbf{t}_{x} \in \operatorname{Tm} \gamma \cdot \gamma_{x} s_{x}$ for the term in $\mathbf{t}$ at variable $x$.

$$
h: \delta \rightarrow s \in \Sigma \cup \gamma \frac{\mathbf{t} \in \operatorname{Sp} \gamma \delta}{h(\mathbf{t}) \in \operatorname{Tm} \gamma s} \quad \overline{\varepsilon \in \operatorname{Sp} \gamma} . \quad \frac{\mathbf{t} \in \operatorname{Sp} \gamma \delta \quad t \in \operatorname{Tm} \gamma \cdot \gamma^{\prime} s}{\mathbf{t}, \vec{x}_{\gamma^{\prime}} \cdot t \in \operatorname{Sp} \gamma\left(\delta, x: \gamma^{\prime} \rightarrow s\right)}
$$

Example 2. If we take $\Sigma=\lambda:(\mathrm{t}: \mathrm{tm} \rightarrow \mathrm{tm}) \rightarrow \mathrm{tm}$, @ $:(\mathrm{t}: \mathrm{tm}, \mathrm{u}: \mathrm{tm}) \rightarrow \mathrm{tm}$, then $\operatorname{Tm}(\vec{x}: \mathrm{tm})$ tm contains exactly the $\lambda$-term with free variables in $\vec{x}$. This justifies why, unlike in the original formulation of HRS, we do not consider x.t to be a term, as $\lambda(x . t)$ corresponds to a term in the $\lambda$-calculus, but x.t or $y . \lambda(x . t)$ do not. Moreover, this makes the restriction of rules to base types in completely automatic in our formulation.
Remark 1. We present the syntax informally using names and $\alpha$-equivalence as a convenience, but we expect that everything can be formally carried out using deBruijn indices.

Substitution Because of our definition of terms, naive substitution would not work: for instance, syntactically replacing $x$ by $z . S(z)$ and $y$ by 0 in $x(y)$ would yield $(z . S(z))(0)$, which is not a valid term. We instead use hereditary substitution [6], which in this case recursively replaces $z$ by 0 , giving $\mathrm{S}(0)$. This is defined by the following clauses, by lexographic induction on $\gamma_{2}$ and the expression being substituted. In the following, we write just $e[\mathbf{t}]$ instead of $e[\mathrm{t} / \delta]$ if no ambiguity arises.

$$
\begin{aligned}
& -\left[-/ \gamma_{2}\right]: \operatorname{Tm} \gamma_{1} \cdot \gamma_{2} \cdot \gamma_{3} s \rightarrow \operatorname{Sp} \gamma_{1} \gamma_{2} \rightarrow \operatorname{Tm} \gamma_{1} \cdot \gamma_{3} s \\
& x(\mathbf{v})\left[\mathbf{u} / \gamma_{2}\right]:=v\left[\mathbf{v}\left[\mathbf{u} / \gamma_{2}\right] / \delta\right] \\
& h(\mathbf{v})\left[\mathbf{u} / \gamma_{2}\right]:=h\left(\mathbf{v}\left[\mathbf{u} / \gamma_{2}\right]\right) \\
& -\left[-/ \gamma_{2}\right]: \operatorname{Sp} \gamma_{1} \cdot \gamma_{2} \cdot \gamma_{3} \delta \rightarrow \operatorname{Sp} \gamma_{1} \gamma_{2} \rightarrow \operatorname{Sp} \gamma_{1} \cdot \gamma_{3} \delta \\
& \varepsilon\left[\mathbf{u} / \gamma_{2}\right]:=\varepsilon \\
& (\mathbf{v}, \vec{y} . t)\left[\mathbf{u} / \gamma_{2}\right]:=\mathbf{v}\left[\mathbf{u} / \gamma_{2}\right], \vec{y} . t\left[\mathbf{u} / \gamma_{2}\right]
\end{aligned}
$$

$$
x(\mathbf{v})\left[\mathbf{u} / \gamma_{2}\right]:=v\left[\mathbf{v}\left[\mathbf{u} / \gamma_{2}\right] / \delta\right] \quad \text { if } x: \delta \rightarrow s \in \gamma_{2} \text { and } \mathbf{u}_{x}=v
$$

Sometimes we need a spine $\mathbf{v} \in \operatorname{Sp} \gamma \gamma$ that satisfies $e[\mathbf{v}]=e$ for all $e$. Normally one takes $\mathbf{v}=\vec{x}_{\gamma}$, but in general this is not a valid spine. Instead, we need to define the identity spine $\mathrm{id}_{\gamma} \in \operatorname{Sp} \gamma \gamma$ by id ${ }_{(\cdot)}:=\varepsilon$ and $\operatorname{id}_{\gamma, x: \delta \rightarrow s}:=\mathrm{id}_{\gamma}, \vec{y}_{\delta} . x$ (id $_{\delta}$. Intuitively, it $\eta$-expands each variable in $\vec{x}_{\gamma}$ so that the resulting sequence is indeed a valid spine. We can now verify that $e\left[\mathrm{id}_{\gamma}\right]=e$ for all $e \in \operatorname{Expr} \gamma$, and moreover $\mathrm{id}_{\delta}[\mathbf{t}]=\mathbf{t}$ for all $\mathbf{t} \in \operatorname{Sp} \gamma \delta$.
Rewriting Given an expression $e$, we write Pos $e$ for its set of positions and FPos $e$ for its set of functional positions. For each $p \in \operatorname{Pos} e$ let $\gamma_{p} \in$ Scope be the scope introduced between the root and $p$, and $s_{p} \in \mathcal{S}$ the sort at $p$. Given $e \in \operatorname{Expr} \gamma$ and $p \in \operatorname{Pos} e$ we write $\left.e\right|_{p} \in \operatorname{Tm} \gamma \cdot \gamma_{p} s_{p}$ for the subterm at position $p$, and given a term $t \in \operatorname{Tm} \gamma \cdot \gamma_{p} s_{p}$ we write $e\{t\}_{p}$ for the result of replacing $\left.e\right|_{p}$ by $t$ in $e$.

A pattern $e \in \operatorname{Patt} \gamma \gamma^{\prime}$ is an expression $e \in \operatorname{Expr} \gamma \cdot \gamma^{\prime}$ in which each variable $x \in \gamma$ appearing at position $p$ occurs applied to id ${\gamma^{\prime \prime}}$ where $\gamma^{\prime \prime} \sqsubseteq \gamma^{\prime} \cdot \gamma_{p}$. We think of variables in $\gamma$ as flexible and $\gamma^{\prime}$ as rigid. We write $t \in \operatorname{Tm}^{\mathrm{P}} \gamma \gamma^{\prime} s$ for a term pattern and $\mathbf{t} \in \mathrm{Sp}^{\mathrm{P}} \gamma \gamma^{\prime} \delta$ for a spine pattern. We have $\operatorname{Tm}^{\mathrm{P}} \gamma \gamma^{\prime} s \subseteq \operatorname{Tm} \gamma \cdot \gamma^{\prime} s$ and $\mathrm{Sp}^{\mathrm{P}} \gamma \gamma^{\prime} \delta \subseteq \mathrm{Sp} \gamma \cdot \gamma^{\prime} \delta$.

Given a pattern $e \in \operatorname{Patt} \gamma \gamma^{\prime}$, we write $\mathrm{ffv}(e)$ for the subscope of $\gamma$ containing exactly the free flexible variables of $e$. A pattern is linear if any $x \in \operatorname{ffv}(e)$ occurs only once.

A rewrite rule $\gamma \Vdash t \longmapsto u: s$ is given by $t \in \operatorname{Tm}^{\mathrm{P}} \gamma \cdot s$ and $u \in \operatorname{Tm} \gamma s$ st $\gamma=\mathrm{ffv}(t)$ and $t$ is not a variable. It is linear if $l$ is a linear pattern. We define the rewrite relation $e \longrightarrow e^{\prime}$ for $e, e^{\prime} \in \operatorname{Expr} \gamma$ if there is a rewrite rule $\delta \Vdash l \longmapsto r: s$ and position $p \in \operatorname{Pos} e$ and spine $\mathbf{v} \in \operatorname{Sp} \gamma \cdot \gamma_{p} \delta$ such that $s=s_{p}$ and $\left.e\right|_{p}=l[\mathbf{v}]$ and $e^{\prime}=e\{r[\mathbf{v}]\}_{p}$.
Critical pairs Given $t, u \in \operatorname{Tm} \delta . \gamma s$ we call $\delta \mid \gamma \Vdash t=? u: s$ a unification problem. A unifier is a spine $\mathbf{v} \in \operatorname{Sp} \delta^{\prime} \delta$ st $t[\mathbf{v}]=u[\mathbf{v}]$. When $t, u \in \operatorname{Tm}^{\mathrm{P}} \delta \gamma s$, the problem has either a most general unifer (mgu) or no unifier.

It is known that one of the difficulties when going from first order to higher-order rewriting is adapting the definition of critical pairs. Given $\delta_{i} \Vdash l_{i} \longmapsto r_{i}: s_{i}$ and $p \in \mathrm{FPos} l_{1}$, if one tries naively to unify $\delta_{1} \cdot \delta_{2}\left|\gamma_{p} \Vdash l_{1}\right|_{p}=?{ }^{?} l_{2}: s_{2}$, then because the variables in $\gamma_{p}$ introduced between the root and $p$ in $l_{1}$ do not appear in $l_{2}$, any unifier must throw dependencies on such variables away, which is not what is intended. Instead, we first need to add $\gamma_{p}$ as dependencies to the variables appearing in $l_{2}$. This is achieved by a substitution Nipkow calls a $\vec{x}_{\gamma_{p}}$-lifter, but it can also be understood more algebraically.

Given $\gamma, \delta \in$ Scope, we define the exponential scope $\gamma \mapsto \delta \in$ Scope by replacing each entry $x: \gamma_{x} \rightarrow s \in \delta$ by $x^{*}: \gamma \cdot \gamma_{x} \rightarrow s$. We have an evaluation spine pattern eval $_{\gamma, \delta} \in \mathrm{Sp}^{\mathrm{P}}(\gamma \mapsto \delta) \gamma \delta$, containing at entry $x: \gamma_{x} \rightarrow s \in \delta$ the argument $\vec{x}_{\gamma_{x}} \cdot x^{*}\left(\mathrm{id}_{\gamma}\right.$, id $\left._{\gamma_{x}}\right)$. For each $\mathbf{t} \in \operatorname{Sp} \gamma^{\prime} . \gamma \delta$ we define its curryfication cur $\mathbf{t} \in \operatorname{Sp} \gamma^{\prime}(\gamma \hookrightarrow \delta)$ by replacing each entry $\vec{x}_{\gamma_{x}} . t$ in $\mathbf{t}$ by $\vec{x}_{\gamma . \gamma_{x}} . t$. The important property we have is that for all $\mathbf{t} \in \operatorname{Sp} \gamma^{\prime} . \gamma \delta$, cur $\mathbf{t}$ is the unique spine satisfying $\mathbf{t}=$ eval $_{\gamma, \delta}[$ cur $\mathbf{t} / \gamma \mapsto \delta]$. Our notation evidences the fact that $\gamma \mapsto \delta$ is the exponential object in the category of scope and spines, with eval ${ }_{\gamma, \delta}$ its corresponding evaluation morphism.

We can now define overlaps and critical pairs. A pattern $e \in$ Patt $\gamma \gamma^{\prime}$ overlaps a rewrite rule $\delta \Vdash l \longmapsto r: s$ at functional position $p \in \mathrm{FPos} e$ if the unification problem

$$
\gamma \cdot\left(\gamma^{\prime} \cdot \gamma_{p} \mapsto \delta\right)\left|\gamma^{\prime} \cdot \gamma_{p} \Vdash e\right|_{p}=^{?} l\left[\operatorname{eval}_{\gamma^{\prime} \cdot \gamma_{p}, \delta}\right]: s
$$

has a unifier - in which case, it also has a most general one. A pattern overlap is proper if $e=l$ implies $p \neq \varepsilon$. A rule overlap is given by two rules $\delta_{1} \Vdash l_{1} \longmapsto r_{1}: s_{1}$ and $\delta_{2} \Vdash l_{2} \longmapsto r_{2}: s_{2}$ and a functional position $p \in \mathrm{FPos} l_{1}$ st $l_{1}$ properly overlaps $l_{2} \longmapsto r_{2}$ at position $p$. Each rule overlap gives rise to a critical pair $\left\langle r_{1}[\mathbf{v}], l_{1}\left\{r_{2}\left[\text { eval } \gamma_{p}, \delta_{2}\right]\right\}_{p}[\mathbf{v}]\right\rangle$, where $\mathbf{v}$ is the mgu of the associated unification problem.
Superdevelopments Like with many proofs of confluence, ours will employ Aczel's superdevelopments [1], defined by the following rules.

$$
\begin{gathered}
\delta \Vdash l \longmapsto r: s \in \mathcal{R} \frac{f(\mathbf{u})=l[\mathbf{v}] \quad \mathbf{t} \Longrightarrow \mathbf{u} \in \operatorname{Sp} \gamma \delta_{f}}{f(\mathbf{t}) \Longrightarrow r[\mathbf{v}] \in \operatorname{Tm} \gamma s} \quad h: \delta \rightarrow s \in \gamma \text { or } \Sigma \frac{\mathbf{v} \Longrightarrow \mathbf{v}^{\prime} \in \operatorname{Sp} \gamma \delta}{h(\mathbf{v}) \Longrightarrow h\left(\mathbf{v}^{\prime}\right) \in \operatorname{Tm} \gamma s} \\
\\
\hline \varepsilon \Longrightarrow \varepsilon \in \operatorname{Sp} \gamma
\end{gathered} \quad \frac{\mathbf{t} \Longrightarrow \mathbf{t}^{\prime} \in \operatorname{Sp} \gamma \delta \quad t \Longrightarrow t^{\prime} \in \operatorname{Tm} \gamma \cdot \gamma_{x} s}{\mathbf{t}, \vec{x}_{\gamma_{x}} . t \Longrightarrow \mathbf{t}^{\prime}, \vec{x}_{\gamma_{x}} \cdot t^{\prime} \in \operatorname{Sp} \gamma\left(\delta, x: \gamma_{x} \rightarrow s\right)}
$$

Recall that we have $\longrightarrow \subseteq \Longrightarrow \subseteq \longrightarrow{ }^{*}$ and thus $\longrightarrow{ }^{*}=\Longrightarrow^{*}$. Moreover, superdevelopments are closed under substitution: if $e \Longrightarrow e^{\prime} \in \operatorname{Expr} \gamma_{1} \cdot \gamma_{2} \cdot \gamma_{3}$ and $\mathbf{u} \Longrightarrow \mathbf{u}^{\prime} \in \operatorname{Sp} \gamma_{1} \gamma_{2}$ then $e\left[\mathbf{u} / \gamma_{2}\right] \Longrightarrow e^{\prime}\left[\mathbf{u}^{\prime} / \gamma_{2}\right] \in \operatorname{Expr} \gamma_{1} \cdot \gamma_{3}$. The following proposition is at the heart of most proofs of confluence by orthogonality 8]. We will also need it to show our criterion.
Proposition 1. Let $e \in \operatorname{Patt} \delta \gamma^{\prime}$ be a linear pattern that does not overlap any lhs of $\mathcal{R}$ and suppose that for some $\mathbf{v} \in \mathrm{Sp} \gamma \delta$ and $e^{\prime}$ we have $e[\mathbf{v} / \delta] \Longrightarrow e^{\prime}$. Then we have $\mathbf{v}^{\prime} \Longrightarrow \mathbf{v}^{\prime \prime} \in \operatorname{Sp} \gamma$ ffv $(e)$ with $\mathbf{v}^{\prime}$ a subspine of $\mathbf{v}$ and $e\left[\mathbf{v}^{\prime \prime} / \mathrm{ffv}(e)\right]=e^{\prime}$.
Corollary 1. Let $\delta \Vdash l \longmapsto r: s$ be a linear rule that does not overlap any rule in $\mathcal{R}$. If $l[\mathbf{v}]=f(\mathbf{t})$ and $\mathbf{t} \Longrightarrow \mathbf{t}^{\prime} \in \operatorname{Sp} \gamma \delta_{f}$, then there is $\mathbf{v}^{\prime}$ with $\mathbf{v} \Longrightarrow \mathbf{v}^{\prime} \in \operatorname{Sp} \gamma \delta$ st $l\left[\mathbf{v}^{\prime}\right]=f\left(\mathbf{t}^{\prime}\right)$.

## 3 A confluence criterion for non-left linearity

Define the order of an arity, of a scope and of a signature by $\operatorname{ord}(\gamma \rightarrow s)=1+\operatorname{ord}(\gamma)$, $\operatorname{ord}(\cdot)=-1, \operatorname{ord}(\gamma, x: \tau)=\max \{\operatorname{ord}(\gamma), \operatorname{ord}(\tau)\}, \operatorname{ord}(\Sigma, c: \tau)=\max \{\operatorname{ord}(\Sigma), \operatorname{ord}(\tau)\}$. Note then that the variables of order zero are the ones whose arity is just a sort.

One can remark that for most rewrite systems of interest the underlying signature $\Sigma$ is of order $\leq 2$, and variables of order $>0$ are only needed for defining the rewrite rules. For instance, this is the case of the $\lambda$-calculus, where one needs a 1 st order variable t to play the role of a metavariable in the rule $\lambda(x . \mathrm{t}(x))_{@ u} \longmapsto \mathrm{t}(\mathrm{u})$, but when translating a $\lambda$-term into its HRS representation one only uses zero order variables. This is also the case of most logics and type theories.

The restriction to signatures of order $\leq 2$ is even baked into the definition of secondorder formalisms, such as in 5. There, one distinguishes between variables (order 0) and metavariables (order 1), and confluence of terms without metavariables is called object confluence. In the following, we rephrase this notion in the setting of 2nd order HRSs.

Suppose now that the underlying signature $\Sigma$ is of order $\leq 2$. A term $t \in \operatorname{Tm} \gamma s$ is an object term $t$ if $\operatorname{ord}(\gamma) \leq 0$. A spine $\mathbf{t} \in \operatorname{Sp} \gamma \delta$ is an object spine if $\operatorname{ord}(\gamma) \leq 0$ and $\operatorname{ord}(\delta) \leq 1$. We refer to them generically as object expressions. Note that if $e$ is an object expression then all terms and spines appearing in $e$ are object expressions. Indeed, because $\Sigma$ is of order at most 2 , each constructor $f$ can only bind 0 -order variables. A rewrite system $\mathcal{R}$ is object confluent if the rewriting relation restricted to object expressions is confluent.

Given two sorts $s, s^{\prime}$ we say that $s$ is accessible from $s^{\prime}$ (written $s^{\prime} \leq s$ ) if there is some object term $t$ of sort $s$ and position $p$ such that $\left.t\right|_{p}$ is of sort $s^{\prime}$. Given a rewrite system $\mathcal{R}$ we write $\mathcal{R} \leq s$ if for some $\delta \Vdash l \longmapsto r: s^{\prime}$ we have $s^{\prime} \leq s$. Note that this notion is only
interesting because we only consider object terms: if one has access to all variables, the condition is always verified by taking $t=x(y)$ with $x: s^{\prime} \rightarrow s$ and $y: s^{\prime}$. It is easy to see that accessibility is decidable when the signature is finite.

Lemma 1. If $t \in \operatorname{Tm} \gamma s$ is an object term and $t \Longrightarrow \mathcal{R} t^{\prime}$ with $\mathcal{R} \nsubseteq s$ then $t=t^{\prime}$.
The heart of our proof is the following proposition, which is very similar to Proposition 1 but replaces linearity by an inaccessibility condition.
Proposition 2. Let $e \in \operatorname{Patt} \delta \gamma^{\prime}$ be a pattern that does not overlap any lhs of $\mathcal{R}$, with $\operatorname{ord}(\delta) \leq 1$ and such that for any $x: \gamma_{x} \rightarrow s_{x} \in \delta$ occurring non-linearly in $e$ we have $\mathcal{R} \not \leq s_{x}$. If for some $\mathbf{v} \in \operatorname{Sp} \gamma \delta$ and $e^{\prime}$ we have $e[\mathbf{v} / \delta] \Longrightarrow e^{\prime}$ with $e[\mathbf{v} / \delta]$ an object expression, then we have $\mathbf{v}^{\prime} \Longrightarrow \mathbf{v}^{\prime \prime} \in \operatorname{Sp} \gamma \operatorname{ffv}(e)$ with $\mathbf{v}^{\prime}$ a subspine of $\mathbf{v}$ and $e\left[\mathbf{v}^{\prime \prime} / \mathrm{ffv}(e)\right]=e^{\prime}$.

Proof. We replay the proof of Proposition 1, but in the case $e=\mathbf{t}, \vec{x}_{\gamma_{x}} . t$ we use Lemma 1 to merge the substitution spines for $\mathbf{t}$ and $t$.

Corollary 2. Let $\delta \Vdash l \longmapsto r: s$ be a rule that does not overlap any rule in $\mathcal{R}$, and such that for any $x: \gamma_{x} \rightarrow s_{x} \in \delta$ occurring non-linearly in $l$ we have $\mathcal{R} \npreceq s_{x}$. If $l[\mathbf{v}] \in \operatorname{Tm} \gamma s$ is an object term with $l[\mathbf{v}]=f(\mathbf{t})$ and $\mathbf{t} \Longrightarrow_{\mathcal{R}} \mathbf{t}^{\prime} \in \operatorname{Sp} \gamma \delta_{f}$ then we have $\mathbf{v} \Longrightarrow{ }_{\mathcal{R}} \mathbf{v}^{\prime} \in \operatorname{Sp} \gamma \delta$ and $l\left[\mathbf{v}^{\prime}\right]=f\left(\mathbf{t}^{\prime}\right)$.

We are now ready to give our criterion.
Theorem 1. Let $\mathcal{R}_{l}$ and $\mathcal{R}_{n l}$ be two rewriting systems on $\Sigma$ with $\operatorname{ord}(\Sigma) \leq 2$ such that
(A) $\mathcal{R}_{n l}$ and $\mathcal{R}_{l}$ are object confluent
(B) $\mathcal{R}_{l}$ is left-linear
(C) There are no critical pairs between $\mathcal{R}_{l}$ and $\mathcal{R}_{n l}$
(D) For each $\delta \Vdash t \longmapsto u: s \in \mathcal{R}_{n l}$ and $x: \gamma_{x} \rightarrow s_{x} \in \delta$ with $x$ occurring non-linearly in $t$, we have $\mathcal{R}_{l} \nsubseteq s_{x}$

Then $\mathcal{R}_{l} \cup \mathcal{R}_{n l}$ is object confluent.
Proof. Because $\mathcal{R}_{n l}$ and $\mathcal{R}_{l}$ are both object confluent, it suffices to show that $\mathcal{R}_{n l}$ and $\mathcal{R}_{l}$ commute on object expressions. We show $\mathcal{R}_{n l} \Longleftarrow \Longrightarrow \mathcal{R}_{l} \subseteq \mathcal{R}_{l} \mathcal{R}_{n l} \Longleftarrow$ on object expressions, by induction on the superdevelopments. The proof is essentially the same as the one for orthogonal systems [8], but using Corollary 2 for the case $f(\mathbf{t}) \Longrightarrow \mathcal{R}_{n l} r[\mathbf{v}]$.

We can now prove that the system of Example 1 is object confluent. First note that $\Sigma$ is second-order as required. Then, by taking $\mathcal{R}_{l}=\left\{\lambda(x . \mathrm{t}(x))_{@} \mathrm{u} \longmapsto \mathrm{t}(\mathrm{u})\right\}$ and $\mathcal{R}_{n l}=\mathcal{R}_{\lambda \pi \uparrow} \backslash \mathcal{R}_{l}$, we have that $\mathcal{R}_{l}$ is confluent by orthogonality and $\mathcal{R}_{n l}$ is confluent by joining its critical pairs and seeing that it is also strongly normalizing. Therefore, both are also object confluent. Moreover, $\mathcal{R}_{l}$ is linear and there are no critical pairs between $\mathcal{R}_{l}$ and $\mathcal{R}_{n l}$. Finally, we can easily verify that there is no object term of sort Ivl containing a subterm of sort tm, and thus we have $\mathcal{R}_{l} \npreceq \mid \mathrm{lvI}$. Hence, by our criterion $\mathcal{R}_{\lambda \pi^{\uparrow}}=\mathcal{R}_{l} \cup \mathcal{R}_{n l}$ is object confluent.

Final remarks Our theorem could instead be stated for second-order formalisms like 5. $4]$ - these correspond roughly to the second-order fragment of HRSs. There, the notion of object confluence is arguably more natural, as the restriction to 0 order variables is built in the formalism.

Finally, the criterion is designed for situations in which we can split the rewrite system into two parts: one that is s.n. but not left-linear (whose confluence can hopefully be shown with the critical pair lemma), and one that is left-linear but (possibly) not s.n. (whose confluence can hopefully be shown with criteria assuming left-linearity). Nevertheless, the condition ( $B$ ) could also be replaced by a condition similar to ( $D$ ), making symmetric the roles of the two systems in the theorem. However, we do not know of any interesting examples for which this generalization would apply.

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# Higher-Order LCTRSs and Their Termination 

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## 1 Introduction

Logically constrained term rewriting systems (LCTRSs) 4, 1 are a formalism for analyzing programs. In real-world programming, data types such as integers, as opposed to natural numbers, and arrays are prevalent. Any practical program analyzing technique should be prepared to handle these. One of the defining features of the LCTRS formalism is its native support for such data types, which are not (co)inductively defined and need to be encoded if handled by more traditional TRSs. Another benefit of the formalism is its separation between logical constraints modeling the control flow and other terms representing the program states.

So far, program analysis on the basis of LCTRSs has concerned imperative programs since LCTRSs were introduced as a first-order formalism. We are naturally curious to see if functional programs can also be analyzed by constrained rewriting. What we present here is our ongoing exploration in this direction: First, we define a higher-order variant of the LCTRS formalism, which, despite the absence of lambda abstractions, is capable of representing some real-world functional programs straightforwardly. Then we take a brief look at the termination problem for this new formalism as termination analysis is by itself an important aspect of program analysis as well as a prerequisite for determining some other properties.

## 2 LCSTRS

We start defining logically constrained simply-typed term rewriting systems (LCSTRSs) with types and terms. We postulate a set $\mathcal{S}$, whose elements we call sorts, and a subset $\mathcal{S}_{\vartheta}$ of $\mathcal{S}$, whose elements we call theory sorts. The set $\mathcal{T}$ of types and its subset $\mathcal{T}_{\vartheta}$, called the set of theory types, are generated as follows: $\mathcal{T}::=\mathcal{S} \mid(\mathcal{T} \rightarrow \mathcal{T})$ and $\mathcal{T}_{\vartheta}::=\mathcal{S}_{\vartheta} \mid\left(\mathcal{S}_{\vartheta} \rightarrow \mathcal{T}_{\vartheta}\right)$. Rightassociativity is assigned to $\rightarrow$ so we can omit some parentheses in types. We assume given disjoint sets $\mathcal{F}$ and $\mathcal{V}$, whose elements we call function symbols and variables, respectively. The grammar $\mathbb{T}::=\mathcal{F}|\mathcal{V}|(\mathbb{T} \mathbb{T})$ generates the set $\mathbb{T}$ of pre-terms. Left-associativity is assigned to the juxtaposition operation in the above grammar so $t_{0} t_{1} t_{2}$ stands for $\left(\left(t_{0} t_{1}\right) t_{2}\right)$, for example. We assume that every function symbol and variable is assigned a unique type. Typing works as expected: if pre-terms $t_{0}$ and $t_{1}$ have types $A \rightarrow B$ and $A$, respectively, $t_{0} t_{1}$ has type $B$. Pre-terms having a type are called terms. We write $t: A$ if a term $t$ has type $A$. We postulate a subset $\mathcal{F}_{\vartheta}$ of $\mathcal{F}$, whose elements we call theory (function) symbols, and assume that theory symbols have theory types. Terms constructed with only theory symbols and variables are called logical terms. The set of variables in a term $t$, denoted by $\operatorname{Var}(t)$, is defined as follows: $\operatorname{Var}(f)=\emptyset, \operatorname{Var}(x)=\{x\}$ and $\operatorname{Var}\left(t_{0} t_{1}\right)=\operatorname{Var}\left(t_{0}\right) \cup \operatorname{Var}\left(t_{1}\right)$. A term $t$ is called a ground term if $\operatorname{Var}(t)=\emptyset$. Note that ground logical terms always have theory types.

Logical terms are distinguished because they will be treated specially when we define the rewrite relation. First, let us define the interpretation of ground logical terms. We postulate an $\mathcal{S}_{\vartheta}$-indexed family of sets $\left(\mathfrak{X}_{A}\right)_{A \in \mathcal{S}_{\vartheta}}$, and extend it to a $\mathcal{T}_{\vartheta}$-indexed family of sets by letting $\mathfrak{X}_{A \rightarrow B}$ be the set of maps from $\mathfrak{X}_{A}$ to $\mathfrak{X}_{B}$. Now we assume given a $\mathcal{T}_{\vartheta}$-indexed family of maps $\left(\llbracket \rrbracket_{A}\right)_{A \in \mathcal{T}_{\vartheta}}$ where $\llbracket \cdot \rrbracket_{A}$ assigns to each theory symbol whose type is $A$ an element of $\mathfrak{X}_{A}$ and is
bijective if $A \in \mathcal{S}_{\vartheta}$. Theory symbols whose type is a theory sort are called values. We extend each indexed map $\llbracket \cdot \rrbracket_{B}$ to a map that assigns to each ground logical term whose type is $B$ an element of $\mathfrak{X}_{B}$ by letting $\llbracket t_{0} t_{1} \rrbracket_{B}$ be $\llbracket t_{0} \rrbracket_{A \rightarrow B}\left(\llbracket t_{1} \rrbracket_{A}\right)$. We omit the type and write just $\llbracket \cdot \rrbracket$ whenever the type can be deduced from the context. $\llbracket t \rrbracket$ is called the interpretation of $t$.

A substitution is a type-preserving map from variables to terms. Every substitution $\sigma$ extends to a type-preserving map $\bar{\sigma}$ from terms to terms. We write $t \sigma$ for $\bar{\sigma}(t)$ and define it as follows: $f \sigma=f, x \sigma=\sigma(x)$ and $\left(t_{0} t_{1}\right) \sigma=\left(t_{0} \sigma\right)\left(t_{1} \sigma\right)$. Now we postulate a theory sort $\mathbb{B}$ and theory symbols $\perp: \mathbb{B}$ and $\top: \mathbb{B}$. Let $\mathfrak{X}_{\mathbb{B}}$ be $\{\mathfrak{o}, \mathbf{1}\}$ and assume $\llbracket \perp \rrbracket=\mathfrak{o}$ and $\llbracket \top \rrbracket=1$. A rewrite rule $\ell \rightarrow r[\varphi]$ is a triple where (i) $\ell$ and $r$ are terms which have the same type, (ii) $\ell$ is not a logical term, (iii) $\varphi$ is a logical constraint, i.e., $\varphi$ is a logical term whose type is $\mathbb{B}$ and the type of each variable in $\operatorname{Var}(\varphi)$ is a theory sort, and (iv) the type of each variable in $\operatorname{Var}(r) \backslash \operatorname{Var}(\ell)$ is a theory sort. A substitution $\sigma$ is said to respect a rewrite rule $\ell \rightarrow r[\varphi]$ if $\sigma(x)$ is a value for all $x \in \operatorname{Var}(\varphi) \cup(\operatorname{Var}(r) \backslash \operatorname{Var}(\ell))$ and $\llbracket \varphi \sigma \rrbracket=1$. A set $\mathcal{R}$ of rewrite rules induces a rewrite relation $\rightarrow_{\mathcal{R}}$ on terms such that $t \rightarrow_{\mathcal{R}} t^{\prime}$ if and only if one of the following conditions is true:

- $t=\ell \sigma$ and $t^{\prime}=r \sigma$ for some $\ell \rightarrow r[\varphi] \in \mathcal{R}$ and some substitution $\sigma$ that respects $\ell \rightarrow r[\varphi]$.
- $t=f v_{1} \cdots v_{n}$ where $f$ is a theory symbol but not a value while $v_{i}$ is a value for all $i$, the type of $t$ is a theory sort, and $t^{\prime}$ is the unique value such that $\llbracket f v_{1} \cdots v_{n} \rrbracket=\llbracket t^{\prime} \rrbracket$.
- $t=t_{0} t_{1}, t^{\prime}=t_{0}{ }^{\prime} t_{1}$ and $t_{0} \rightarrow_{\mathcal{R}} t_{0}{ }^{\prime}$.
- $t=t_{0} t_{1}, t^{\prime}=t_{0} t_{1}{ }^{\prime}$ and $t_{1} \rightarrow_{\mathcal{R}} t_{1}{ }^{\prime}$.

Logical constraints are essentially first-order-higher-order variables are excluded and theory symbols take only first-order arguments. We adopt this restriction because many conditions in functional programs are still first-order and solving higher-order constraints is hard. That is not to say that higher-order constraints are of no interest; we simply leave them out of the scope of LCSTRSs.

Below is an example LCSTRS:

$$
\begin{array}{clll}
\text { init } \rightarrow \text { fact } n \text { exit } & {[\top]} & \text { fact } n k \rightarrow k 1 & {[n \leq 0]} \\
\text { comp } g f x \rightarrow g(f x) & {[\top]} & \text { fact } n k \rightarrow \text { fact }(n-1)(\operatorname{comp} k(* n)) & {[n>0]}
\end{array}
$$

Here init and exit denote the start and the end of the program, respectively. The core of the program is fact, which computes the factorial function in continuation-passing style, and comp is an auxiliary function for function composition. Integer literals and operators are theory symbols. Note that we use infix notation to improve readability. The occurrence of $n$ in the rewrite rule defining init is an example of a variable that occurs on the right-hand side but not on the left-hand side of a rewrite rule. Such variables can be used to model user input.

Let $\mathcal{R}$ denote the set of rewrite rules in the example and consider the rewrite sequence
fact 1 exit $\rightarrow_{\mathcal{R}}$ fact $(1-1)(\operatorname{comp}$ exit $(* 1)) \rightarrow_{\mathcal{R}}$ fact $0($ comp exit $(* 1)) \rightarrow_{\mathcal{R}}$ comp exit $(* 1) 1$.
In the second step, no rewrite rule is invoked. Such rewrite steps are called calculation steps. We can write $\rightarrow_{\emptyset}$ for a calculation step. Terms $s$ and $t$ are said to be joinable by $\rightarrow_{\emptyset}$, written as $s \downarrow_{\emptyset} t$, if there exists a term $r$ such that $s \rightarrow_{\emptyset}^{*} r$ and $t \rightarrow_{\emptyset}^{*} r$.

## 3 Termination

In order to prove that a given (unconstrained) TRS $\mathcal{R}$ is terminating, we usually look for a stable, monotonic and well-founded relation $\succ$ which orients every rewrite rule in $\mathcal{R}$, i.e., $\ell \succ r$ for all $\ell \rightarrow r \in \mathcal{R}$. This standard technique, however, requires a few tweaks to be applied to LCSTRSs. First, stability should be tightly coupled with rule orientation because every rewrite rule in an LCSTRS is equipped with a logical constraint, which decides what substitutions are expected when the rewrite rule is invoked. Therefore, we say that a type-preserving relation $\succ$ on terms orients a rewrite rule $\ell \rightarrow r[\varphi]$ if $\ell \sigma \succ r \sigma$ for each substitution $\sigma$ that respects the rewrite rule. Second, the monotonicity requirement can be weakened because $\ell$ is never a logical term in a rewrite rule $\ell \rightarrow r[\varphi]$. We say that a type-preserving relation $\succ$ on terms is rule-monotonic if $t_{0} \succ t_{0}{ }^{\prime}$ implies $t_{0} t_{1} \succ t_{0}{ }^{\prime} t_{1}$ when $t_{0}$ is not a logical term, and $t_{1} \succ t_{1}{ }^{\prime}$ implies $t_{0} t_{1} \succ t_{0} t_{1}{ }^{\prime}$ when $t_{1}$ is not a logical term.

We present a tentative definition of HORPO 2 on LCSTRSs. For each theory sort $A$, we postulate theory symbols $\sqsupset_{A}: A \rightarrow A \rightarrow \mathbb{B}$ and $\sqsupseteq_{A}: A \rightarrow A \rightarrow \mathbb{B}$ such that $\llbracket \sqsupset_{A} \rrbracket$ is a wellfounded ordering on $\mathfrak{X}_{A}$ and $\llbracket \sqsupseteq_{A} \rrbracket$ is the reflexive closure of $\llbracket \sqsupset_{A} \rrbracket$. We omit the sort and write just $\sqsupset$ and $\sqsupseteq$ whenever the sort can be deduced from the context. Given the precedence $\square$, a well-founded ordering on function symbols such that $f \triangleright g$ for all $f \in \mathcal{F} \backslash \mathcal{F}_{\vartheta}$ and $g \in \mathcal{F}_{\vartheta}$, and the status stat, a map from $\mathcal{F}$ to $\left\{\mathfrak{l}, \mathfrak{m}_{2}, \mathfrak{m}_{3}, \ldots\right\}$, the higher-order recursive path ordering (HORPO) $\left(\succsim_{\varphi}, \succ_{\varphi}\right)$ is a family of type-preserving relation pairs on terms indexed by logical constraints and defined as follows:

- $s \succsim_{\varphi} t$ if and only if one of the following conditions is true:
$-s$ and $t$ are logical terms whose type is a theory sort, $\operatorname{Var}(\varphi) \supseteq \operatorname{Var}(s) \cup \operatorname{Var}(t)$ and $\varphi \models \sqsupseteq s t$.
$-s \succ_{\varphi} t$.
$-s \downarrow_{\emptyset} t$.
$-s$ is not a logical term, $s=s_{1} s_{2}, t=t_{1} t_{2}, s_{1} \succsim_{\varphi} t_{1}$ and $s_{2} \succsim_{\varphi} t_{2}$.
- $s \succ_{\varphi} t$ if and only if one of the following conditions is true:
$-s$ and $t$ are logical terms whose type is a theory sort, $\operatorname{Var}(\varphi) \supseteq \operatorname{Var}(s) \cup \operatorname{Var}(t)$ and $\varphi \vDash \sqsupset s t$.
$-s$ and $t$ have the same type and $s \triangleright_{\varphi} t$.
$-s$ is not a logical term, $s=x s_{1} \cdots s_{n}$ where $x$ is a variable, $t=x t_{1} \cdots t_{n}, s_{i} \succsim_{\varphi} t_{i}$ for all $i$ and there exists $i$ such that $s_{i} \succ_{\varphi} t_{i}$.
- $s \triangleright_{\varphi} t$ if and only if $s$ is not a logical term, $s=f s_{1} \cdots s_{m}$ where $f$ is a function symbol, and one of the following conditions is true:
$-s_{i} \succsim \varphi t$ for some $i$.
$-t=t_{0} t_{1} \cdots t_{n}$ and $s \triangleright_{\varphi} t_{i}$ for all $i$.
$-t=g t_{1} \cdots t_{n}, f \triangleright g$ and $s \triangleright_{\varphi} t_{i}$ for all $i$.
$-t=f t_{1} \cdots t_{n}, \operatorname{stat}(f)=\mathfrak{l}, s_{1} \cdots s_{m} \succ_{\varphi}^{\mathfrak{l}} t_{1} \cdots t_{n}$ and $s \triangleright_{\varphi} t_{i}$ for all $i$.
$-t=f t_{1} \cdots t_{n}, \operatorname{stat}(f)=\mathfrak{m}_{k}, k \leq n, s_{1} \cdots s_{\min (m, k)} \succ_{\varphi}^{\mathfrak{m}} t_{1} \cdots t_{k}$ and $s \triangleright_{\varphi} t_{i}$ for all $i$.

In the above, $s_{1} \cdots s_{m} \succ_{\varphi}^{l} t_{1} \cdots t_{n}$ if and only if $\exists i \leq \min (m, n)\left(s_{i} \succ_{\varphi} t_{i} \wedge \forall j<i s_{j} \succsim \varphi t_{j}\right)$, $\succ_{\varphi}^{\mathfrak{m}}$ is the generalized multiset extension of $\left(\succsim \varphi, \succ_{\varphi}\right)$ (see [3]), and $\varphi \models \varphi^{\prime}$ denotes, on the assumption that $\varphi$ and $\varphi^{\prime}$ are logical constraints such that $\operatorname{Var}(\varphi) \supseteq \operatorname{Var}\left(\varphi^{\prime}\right)$, that for each substitution $\sigma$ which maps variables in $\operatorname{Var}(\varphi)$ to values, $\llbracket \varphi \sigma \rrbracket=1$ implies $\llbracket \varphi^{\prime} \sigma \rrbracket=1$.

The design is that $\succ_{T}$ should orient a rewrite rule $\ell \rightarrow r[\varphi]$ if $\ell \succ_{\varphi} r$. Then once a combination of $\sqsupset$, and stat that guarantees $\ell \succ_{\varphi} r$ for all $\ell \rightarrow r[\varphi] \in \mathcal{R}$ is present, we can conclude that the LCSTRS $\mathcal{R}$ is terminating. The soundness of this method relies on the following properties of $\succ_{\varphi}$, which we must prove:

- $\succ_{\mathrm{T}}$ orients $\ell \rightarrow r[\varphi]$ if $\ell \succ_{\varphi} r$.
- $\succ_{\mathrm{T}}$ is rule-monotonic.
- $\succ_{\mathrm{T}}$ is well-founded.
- $\rightarrow_{\emptyset} ; \succ_{\mathrm{T}} \subseteq \succ_{\mathrm{T}}$.

Note that $\rightarrow_{\emptyset}$ is well-founded because the size strictly decreases through every calculation step. Consider the example LCSTRS given in the previous section. Any combination of $\sqsupset$, and stat that satisfies the following properties would witness the well-foundedness of $\rightarrow_{\mathcal{R}}$ : $\llbracket \sqsupset \rrbracket=\lambda x y . x>0 \wedge x>y$, init fact comp, init exit and stat $($ fact $)=\mathfrak{l}$.

## 4 Future Work

LCSTRSs are still a work in progress. While the formalism itself is in a somewhat stable state, the above method for termination analysis is in active development. First and foremost, we need to prove that HORPO on LCSTRSs has the expected properties. When the theory is complete, we would like to make a tool to automate the finding of HORPO on LCSTRSs. It would also be interesting to explore other methods for termination analysis on the new formalism, including StarHorpo [3] (a transitive variant of HORPO), interpretation-based methods and dependency pairs. Another direction is to go beyond LCSTRSs by augmenting the formalism with lambda abstractions or higher-order constraints.

## References

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# Modular Termination for Second-Order Rewriting Systems and Application to Effect Handlers 

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#### Abstract

We present a new modular proof method of termination for second-order computation. The proof method is useful for proving termination of higher-order foundational calculi. To establish the method, we use a variation of the semantic labelling translation and Blanqui's General Schema: a syntactic criterion of strong normalisation. As an application, we show termination of a variant of call-by-push-value calculus with algebraic effects, an effect handler and effect theory. This is based on the author's paper "Modular Termination for Second-Order Computation Rules and Application to Algebraic Effect Handler", published in Logical Methods in Computer Science, Vol. 18, Issue 2, No.8, June 14, 2022.


## 1 Introduction

Computation rules such as the $\beta$-reduction of the $\lambda$-calculus and arrangement of letexpressions are fundamental mechanisms of functional programming. Computation rules for modern functional programming are necessarily higher-order and are presented as a $\lambda$-calculus extended with extra rules such as rules of let-expressions or first-order algebraic rules like " $0+x \rightarrow x$ ".

The termination property is one of the most important properties of such a calculus because it is a key to ensuring the decidability of its properties. A powerful termination checking method is important in theory and in practice. Termination is ideally checked modularly. However, in general, strong normalisation is not a modular property [Toy87].

In this work we establish a new modular termination proof method of the following form: if $\mathbf{A}$ is SN and $\mathbf{B}$ is SN with some suitable conditions, then $\mathcal{C}=\mathbf{A} \uplus \mathbf{B}$ is SN. As an application of the modular termination proof method, we give a termination proof of effectful calculus using a variant of Levy's call-by-push value (CBPV) calculus [Lev06] called multi-adjunctive metalanguage (MAM) [FKLP19] with effect handlers and effect theory [PP13].

## 2 Main Theorem

We use a formal framework of second-order computation based on second-order algebraic theories [FH10]. This framework has been used in [Ham19, HAK20]. A computation system (CS) is a pair $(\Sigma, \mathcal{C})$ of a signature and a set $\mathcal{C}$ of computation rules. We write $s \Rightarrow_{\mathcal{C}} t$ to be one-step computation using $\mathcal{C}$.

Assumption 2.1. Let $\left(\Sigma_{\mathbf{A}} \uplus \Theta, \mathbf{A}\right)$ and $\left(\Sigma_{\mathbf{A}} \uplus \Sigma_{\mathbf{B}} \uplus \Theta, \mathbf{B}\right)$ be computation systems satisfying:
(i) $\Sigma_{\mathbf{A}}$ is the set of defined function symbols of $\mathbf{A}$.
(ii) $\Sigma_{\mathbf{B}}$ is the set of defined function symbols of $\mathbf{B}$.
(iii) $\Theta$ is the signature for constructors of $\mathcal{C}$, where $\mathcal{C} \triangleq \mathbf{A} \uplus \mathbf{B}$.
(iv) $\mathcal{C}$ is finitely branching.
(v) Both sides of each rule in $\mathcal{C}$ satisfy the $\Sigma_{\mathbf{A}}$-layer condition.

Definition 2.2. We say that a meta-term $u$ satisfies the $\Sigma_{\mathrm{A}^{\prime}}$-layer condition if

- for every $f(\overline{\bar{x} . t}) \unlhd u$ with $f \in \Sigma_{\mathbf{A}}, \operatorname{Fun}(f(\overline{\bar{x} . t})) \subseteq \Sigma_{\mathbf{A}} \uplus \Theta$ and $\bar{t}$ are second-order patterns, and
- if $u$ is a meta-application $M\left[s_{1}, \ldots, s_{n}\right]$, every $s_{i}$ does not contain function symbols. This condition has been called that $u$ is solid [Ham07].

We say that $\mathbf{A}$ is accessible if for each $f(\overline{\bar{x}} . t) \Rightarrow r \in \mathbf{A}$, every metavariable occurring in $r$ is accessible in some of $\bar{t}$.

The General Schema [Bla00], [Bla16] is a termination criterion of higher-order rewrite rules.
The main theorem is proved by using a variant of higher-order semantic labelling [Ham07] and the General Schema.
Theorem 2.3. (Modular Termination) Let $\left(\Sigma_{\mathbf{A}} \uplus \Theta, \mathbf{A}\right)$ and $\left(\Sigma_{\mathbf{A}} \uplus \Sigma_{\mathbf{B}} \uplus \Theta, \mathbf{B}\right)$ be computation systems satisfying Assumption 2.1 and the following.
(i) $\mathbf{A}$ is accessible.
(ii) $\left(\Sigma_{\mathbf{A}} \uplus \Sigma_{\mathbf{B}} \uplus \Theta \uplus \Sigma_{\text {Proj }}, \mathbf{A}_{\text {Proj }}\right)$ is SN (not necessarily by GS), where $\mathbf{A}_{\text {Proj }}$ is an extension of A with projections of pairs $\left\langle M_{1}, M_{2}\right\rangle \Rightarrow M_{i}(i=1,2)$.
(iii) $\left(\Sigma_{\mathbf{A}} \uplus \Sigma_{\mathbf{B}} \uplus \Theta, \mathbf{B}\right)$ is SN by the General Schema.

Then $\left(\Sigma_{\mathbf{A}} \uplus \Sigma_{\mathbf{B}} \uplus \Theta, \mathbf{A} \uplus \mathbf{B}\right)$ is SN.

## 3 Application: Algebraic Effect Handler with Theory

As an application, we demonstrate that our theorem is useful to prove the termination of a calculus with algebraic effects. The background of this section is as follows. Plotkin and Power introduced the algebraic theory of effects to axiomatise various computational effects [PP02] and they correspond to computational monads of Moggi [Mog88]. Plotkin and Pretnar formulated algebraic effects and handlers [PP13], which provided an alternative to monads as a basis for effectful programming across a variety of functional programming languages.

First, we formulate the multi-adjunctive metalanguage (MAM) [FKLP19] for an effectful $\lambda$ calculus, which is an extension of Levy's call-by-push-value (CBPV) calculus [Lev06]. Secondly, we provide an effect theory. Thirdly, we give an effect handler. We formulate MAM as a secondorder computation system $\left(\Sigma_{\text {MAM }} \uplus \Theta\right.$, MAM $)$. The signature $\Sigma_{\text {MAM }}$ consists of the following defined function symbols

```
bang : U(c) }->\textrm{c
caseP : Pair(a1,a2),(a1,a2 -> c) }->\textrm{c
case : Sum(a1,a2),(a1 ->c),(a2 ->c) ->c
let : F(a),(a -> c) }->\textrm{c
app : Arr(a,c),a -> c
prj1 : CPair(c1,c2) -> c1 ; prj2 : CPair(c1,c2) -> c2
```

and the set of constructors $\Theta$ consists of

```
unit : Unit ; pair : a1,a2 }->\mathrm{ Pair(a1,a2)
inj1 : a1 }->\mathrm{ Sum(a1,a2) ; inj2 : a2 }->\mathrm{ Sum(a1,a2)
cpair : c1,c2 }->\mathrm{ CPair(c1,c2)
thunk : c }->\textrm{U}(\textrm{c}
```

```
return : a }->\textrm{F}(\textrm{a}
lam : (a }->\textrm{b})->\operatorname{Arr}(\textrm{a},\textrm{b}
```

The set MAM of MAM's computation rules is given by ${ }^{1}$

| (beta) | $\operatorname{lam}(x . M[x]) @ V$ | $\Rightarrow M[V]$ |
| :--- | :--- | :--- |
| (u) | $\operatorname{bang}(\operatorname{thunk}(M))$ | $\Rightarrow M$ |
| (prod1) | $\operatorname{prj1} 1(\operatorname{cpair}(M 1, M 2))$ | $\Rightarrow M 1$ |
| (prod2) | $\operatorname{prj2(cpair(M1,M2))}$ | $\Rightarrow M 2$ |
| (caseP) | $\operatorname{caseP}(\operatorname{pair}(V 1, V 2), x 1 . x 2 . M[x 1, x 2])$ | $\Rightarrow M[V 1, V 2]$ |
| (case1) | $\operatorname{case}(\operatorname{inj1(V),x.M1[x],y.M2[y])}$ | $\Rightarrow M 1[V]$ |
| (case2) | $\operatorname{case}(\operatorname{inj2(V),x.M1[x],y.M2[y])}$ | $\Rightarrow M 2[V]$ |
| $(f)$ | $\operatorname{let}(r e t u r n(V), x . M[x])$ | $\Rightarrow M[V]$ |

Using this formulation, SN of MAM is immediate because it satisfies GS.
We define the signature $\Sigma_{\mathrm{Gl}}$ by

```
get : (N -> F(N)) ->F(N)
put : N,F(N) -> F(N)
```

It consists of the operations get(v.t) (looking-up the state, binding the value to v , and continuing $t$ ) and put ( $v, t$ ) (updating the state to $v$ and continuing $t$ ). The theory of global state [PP02, FS14] can be stated as a computation system ( $\Sigma_{\mathrm{Gl}} \uplus\{$ return\}, gstate) defined by

| $(\mathrm{lu})$ | $\operatorname{get}(\mathrm{v} \cdot \operatorname{put}(\mathrm{v}, \mathrm{X}))$ | $\Rightarrow \mathrm{X}$ |
| :--- | :--- | :--- |
| $(\mathrm{ll})$ | $\operatorname{get}(\mathrm{w} \cdot \operatorname{get}(\mathrm{v} \cdot \mathrm{X}[\mathrm{v}, \mathrm{w}]))$ | $\Rightarrow \operatorname{get}(\mathrm{v} \cdot \mathrm{X}[\mathrm{v}, \mathrm{v}])$ |
| $(\mathrm{uu})$ | $\operatorname{put}(\mathrm{V}, \operatorname{put}(\mathrm{W}, \mathrm{X}))$ | $\Rightarrow \operatorname{put}(\mathrm{W}, \mathrm{X})$ |
| $(\mathrm{ul})$ | $\operatorname{put}(\mathrm{V}, \operatorname{get}(\mathrm{w} \cdot \mathrm{X}[\mathrm{w}]))$ | $\Rightarrow \operatorname{put}(\mathrm{V}, \mathrm{X}[\mathrm{V}])$ |

These axioms have intuitive reading. For example, the axiom (lu) says that looking-up the state, binding the value to v , then updating the state to v , is equivalent to doing nothing. The axiom (ul) says that updating the state to V , then looking-up and continuing X with the looked-up value, is equivalent to updating the state to V and continuing X with V .

Plotkin and Power showed that the monad corresponding to the theory of global state (of finitely many locations) is the state monad [PP02]. Although ( $\Sigma_{\mathrm{Gl}} \uplus\{$ return $\}$, gstate) does not satisfy GS, it can be shown to be SN by interpretation [HAK20].

An effect handler provides an implementation of effects by interpreting algebraic effects as actual effects. The handler [KLO13, FKLP19] for effect terms for global states can be formulated as a computation system $\left(\Sigma_{\mathrm{Gl}} \uplus \Sigma_{\mathrm{MAM}} \uplus \Sigma_{\text {Handle }}\right.$, Handle) as follows.

```
handler \(:(N \rightarrow F(N)),(\operatorname{Arr}(N, F(N)) \rightarrow F(N)),(N, F(N) \rightarrow F(N)), F(N) \rightarrow F(N)\)
(h_r) handler(RET, GET,PUT, return(X)) \(\Rightarrow\) RET [X]
(h_g) handler (RET, GET,PUT, get \((x . M[x])) \Rightarrow \operatorname{GET}[\quad \operatorname{lam}(x . h a n d l e r(R E T, G E T, P U T, M[x]))]\)
(h_p) handler (RET, GET,PUT, put (P,M)) \(\Rightarrow\) PUT[P,lam(x.handler(RET,GET,PUT, M))]
```

Now, we consider the main problem of this section: SN of the whole computation system

$$
\begin{equation*}
\left(\Sigma_{\mathrm{Gl}} \uplus \Sigma_{\mathrm{MAM}} \uplus \Sigma_{\text {Handle }} \uplus \Theta \text {, gstate } \uplus \text { MAM } \uplus \text { Handle }\right) \tag{1}
\end{equation*}
$$

[^0]The General Schema does not work to show SN of it because gstate does not satisfy GS. Therefore, we divide it into

$$
\begin{aligned}
\left(\Sigma_{\mathbf{A}} \uplus \Theta, \mathbf{A}\right) & =\left(\Sigma_{\mathrm{Gl}} \uplus \Theta, \text { gstate }\right), \\
\left(\Sigma_{\mathbf{A}} \uplus \Sigma_{\mathbf{B}} \uplus \Theta, \mathbf{B}\right) & =\left(\Sigma_{\mathrm{Gl}} \uplus\left(\Sigma_{\text {MAM }} \uplus \Sigma_{\text {Handle }}\right) \uplus \Theta, \text { MAM } \uplus \text { Handle }\right) .
\end{aligned}
$$

The computation system (1) is not a disjoint union of $\mathbf{A}$ and $\mathbf{B}$, and is actually a hierarchical combination that shares constructors $\Theta$. The lhss of Handle $(\subseteq \mathbf{B})$ involve defined function symbols get,put in $\Sigma_{\mathbf{A}}$.

We apply the modularity Thm. 2.3. Assumption 2.1 is satisfied because the computation system (1) is finitely branching and satisfies the the $\Sigma_{\mathbf{A}}$-layer condition. We check the assumptions. We define the well-founded order on types by

$$
T\left(a_{1}, \ldots, a, \ldots, a_{n}\right)>_{\mathcal{T}} a
$$

for every $n$-ary type constructor $T$, and every type $a$, where the rhs's $a$ is placed at the $i$-th argument for every $i=1, \ldots, n$.
(i) $\mathbf{A}=$ gstate is accessible. This is immediate because of the type comparison for the arguments of get,put,return, which holds by $N<\mathcal{T} F(N)$.
(ii) $\left(\Sigma_{\mathbf{A}} \uplus \Theta \uplus \Sigma_{\text {Proj }}\right.$, gstate $\left.\uplus \operatorname{Proj}\right)$ is SN . This is proved by well-founded interpretation.
(iii) $\left(\Sigma_{\mathbf{A}} \uplus \Sigma_{\mathbf{B}} \uplus \Theta\right.$, MAM $\uplus$ Handle) is SN by GS. This is immediate by applying GS with the precedence

```
handler > > lam
```

to the computation system. The rhss of MAM involve no function symbols and the rhss of Handle involve handler, lam. To check that each recursive call of handler happens with a smaller argument, here we use the structural subterm ordering [Bla16, Def.13] to establish that $M[x]$ is smaller than get (x.M[x]). Every metavariable is accessible.

Hence we conclude that the computation system (1) is SN.

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# The algebraic $\lambda$-calculus is a conservative extension of the ordinary $\lambda$-calculus 

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#### Abstract

The algebraic $\lambda$-calculus is an extension of the ordinary $\lambda$-calculus with linear combinations of terms. We establish that two ordinary $\lambda$-terms are equivalent in the algebraic $\lambda$-calculus iff they are $\beta$-equal. Although this result was originally stated in the early 2000's (in the setting of Ehrhard and Regnier's differential $\lambda$-calculus), the previously proposed proofs were wrong: we explain why previous approaches failed and develop a new proof technique to establish conservativity.


## 1 Introduction

The algebraic $\lambda$-calculus was introduced by the second author [Vau07, Vau09] as a generic framework to study the rewriting theory of the $\lambda$-calculus in presence of weighted superpositions of terms. The latter feature is pervasive in the quantitative semantics of $\lambda$-calculus and linear logic, that have flourished in the past twenty years [Ehr05, Lai +13, DE11, Cas +18 , etc.] and the algebraic $\lambda$-calculus is meant as a unifying syntactic counterpart of that body of works.

The algebraic $\lambda$-calculus was actually obtained by removing the differentiation primitives from Ehrhard and Regnier's differential $\lambda$-calculus ER03], keeping only the dynamics associated with linear combinations of terms. This dynamics is surprisingly subtle in itself: for instance, if 1 has an opposite in the semiring R of coefficients, then the rewriting theory becomes trivial. We refer the reader to the original paper [Vau09] for a thorough discussion, and focus on the question of conservativity only, assuming R is positive - i.e. if $a+b=0$ then $a=b=0$. We briefly outline the main definitions, keeping the same notations as in the former paper, so that the reader can consistently refer to it for a more detailed account if need be.

Overview of the algebraic $\lambda$-calculus. The syntax of algebraic $\lambda$-terms is constructed in two stages. We first consider raw terms, which are terms inductively generated as follows:

$$
\mathrm{L}_{\mathrm{R}} \ni M, N, \ldots::=x|\lambda x . M|(M) N|\mathbf{0}| M+N \mid a \cdot M
$$

where $a$ ranges over the semiring R (beware that we use Krivine's convention for application). We consider raw terms up to $\alpha$-equivalence: $L_{R}$ contains the set $\Lambda$ of pure $\lambda$-terms as a strict subset. We then consider algebraic equality $\triangleq$ on raw terms, which is the congruence generated by the equations of R-module, plus the following linearity axioms:

$$
\begin{array}{rcc}
\lambda x . \mathbf{0} \triangleq \mathbf{0} & \lambda x \cdot(M+N) \triangleq \lambda x \cdot M+\lambda x \cdot N & \lambda x \cdot(a \cdot M) \triangleq a \cdot \lambda x \cdot M \\
(\mathbf{0}) P \triangleq \mathbf{0} & (M+N) P \triangleq(M) P+(N) P & (a \cdot M) P \triangleq a \cdot(M) P
\end{array}
$$

[^1]which reflects the point-wise definition of the sum of functions. Note that, without these equations, a term such as $(\lambda x . M+\lambda x . N) P$ has no redex.

The terms of the algebraic $\lambda$-calculus, called algebraic terms below, are then the $\triangleq$ classes $\sigma=\underline{M}$ of raw terms $M \in \mathrm{~L}_{\mathrm{R}}$. We extend syntactic constructs to algebraic terms (e.g., $\lambda x . \underline{M}=\underline{\lambda x \cdot M}$, which is well defined because $\triangleq$ is a congruence). Among algebraic terms, we distinguish the simple terms, which are intuitively those without sums at top level: a term $\sigma$ is simple if $\sigma=\underline{x}$ for some variable $x$, or $\sigma=\lambda x . \tau$ or $\sigma=(\tau) \rho$ where $\tau$ is itself simple (inductively). In particular, $\underline{M}$ is simple as soon as $M \in \Lambda$. By definition, algebraic terms form an R -module, and it is easy to check that it is freely generated by the set $\Delta_{R}$ of simple terms: we write $R\left\langle\Delta_{R}\right\rangle$ for the module of algebraic terms.

A seemingly natural way to extend the $\beta$-reduction $\rightarrow_{\Lambda}$ of $\lambda$-terms to algebraic terms is to define it contextually on raw terms, and then apply it modulo $\triangleq$ : among other issues with this naïve definition, note that $M \triangleq M+0 . N$ would reduce to $M+0 . N^{\prime} \triangleq M$ for any $N \rightarrow_{\Lambda} N^{\prime}$, so that the obtained reduction would be reflexive and there would be no clear notion of normal form. Ehrhard and Regnier's solution is to rather consider two relations: $\rightarrow \subset \Delta_{R} \times R\left\langle\Delta_{R}\right\rangle$ defined contextually on simple terms with $\beta$-reduction as a base case; and $\rightrightarrows \subset R\left\langle\Delta_{R}\right\rangle \times R\left\langle\Delta_{R}\right\rangle$ on algebraic terms, obtained by setting $\sigma \rightrightarrows \sigma^{\prime}$ iff $\sigma=a . \tau+\rho$ and $\sigma^{\prime}=a . \tau^{\prime}+\rho$ with $\tau \rightarrow \tau^{\prime}$ and $a \neq 0$. Then $\leftrightarrows$ is confluent [ER03: Vau09] and, provided R is positive, an algebraic term is in normal form iff it is the class of a raw term without $\beta$-redex.

Note that, for any fixed point combinator $Y$, by setting $\infty_{\sigma}=(\underline{Y}) \lambda x \cdot(\sigma+\underline{x})$, we obtain $\infty_{\sigma} \leftrightarrow \sigma+\infty_{\sigma}$ where $\leftrightarrow$ is the equivalence on $\mathrm{R}\left\langle\Delta_{R}\right\rangle$ generated by the reduction relation $\widetilde{\rightarrow}$. In case $1 \in \mathrm{R}$ has an opposite -1 , we can now exhibit the above-mentioned inconsistency of the theory: $\underline{\mathbf{0}}=\infty_{\sigma}+(-1) . \infty_{\sigma} \leftrightarrow \sigma$ for any $\sigma$. From now on, we thus assume that R is positive.

Contributions. Our goal is to establish that, for any two $\lambda$-terms $M$ and $N \in \Lambda$, we have $\underline{M} \leftrightarrow \underline{N}$ iff $M \leftrightarrow_{\Lambda} N$, where $\leftrightarrow_{\Lambda}$ is the usual $\beta$-equivalence on $\lambda$-terms. For that purpose, it is sufficient to establish a conservativity result on reduction relations rather than on the induced equivalences: if $\underline{M} \widetilde{\rightarrow}^{*} \underline{N}$ then $M \rightarrow_{\Lambda}^{*} N$. This is our main result, theorem 4.3 below.

In the next section, we explain what was wrong with the previous two attempts, first by Ehrhard and Regnier, then by the second author, to establish conservativity, and we outline the new proof strategy we propose. The rest of the paper is dedicated to the proof of theorem $4.3 \|^{1}$

## 2 Two non-proofs and a new approach

Recall that an ARS (abstract rewriting system) is a pair $(A, \leadsto)$ of a set $A$ and binary relation $\leadsto \subseteq A \times A$. An extension of $(A, \leadsto)$ is another $\operatorname{ARS}\left(A^{\prime}, \sim^{\prime}\right)$ such that $A \subseteq A^{\prime}$ and $\leadsto \subseteq$ $\sim^{\prime}$. This extension is conservative if, for every $a_{1}, a_{2} \in A, a_{1} \leadsto a_{2}$ iff $a_{1} \sim^{\prime} a_{2}$. An equational system is an $\operatorname{ARS}(A, \sim)$ such that $\sim$ is an equivalence relation. Our goal is thus to establish that the equational system $\left(R\left\langle\Delta_{R}\right\rangle, \leftrightarrow\right)$ is a conservative extension of $\left(\Lambda, \leftrightarrow_{\Lambda}\right)$ here we consider the injection $M \in \Lambda \mapsto \underline{M} \in \mathrm{R}\left\langle\Delta_{\mathrm{R}}\right\rangle$ as an inclusion.

In their paper on the differential $\lambda$-calculus [ER03], Ehrhard and Regnier claim that this follows directly from the confluence of $\widetilde{\rightarrow}$, but this argument is not valid: $\widetilde{\rightarrow}$ does contain $\rightarrow_{\Lambda}$, and it is indeed confluent, without any positivity assumption; but we have already stated that $\leftrightarrow$ is inconsistent in presence of negative coefficients, so this observation cannot be sufficient.

[^2]\[

$$
\begin{gathered}
\frac{M \rightarrow_{\Lambda}^{*} x}{M \vdash \underline{x}}(\mathrm{v}) \quad \frac{M \rightarrow_{\Lambda}^{*} \lambda x . N \quad N \vdash \tau}{M \vdash \lambda x . \tau}(\lambda) \quad \frac{M \rightarrow_{\Lambda}^{*}(N) P \quad N \vdash \tau \quad P \Vdash \rho}{M \vdash(\tau) \rho}(\mathrm{a}) \\
\frac{M \vdash \mathbf{0}}{M \Vdash \mathbf{0}) \quad \frac{M \vdash \sigma}{M \Vdash a . \sigma+\tau}(+)}
\end{gathered}
$$
\]

Figure 1: Inference rules for the mashup relations

Ehrhard and Regnier's mistake is certainly an erroneous application of a general conservativity result in Terese's textbook Ter03, missing the fact that Terese's notion of extension is more demanding: for Terese, $(A, \leadsto)$ is a sub-ARS of $\left(A^{\prime}, \sim^{\prime}\right)$ if $A \subseteq A^{\prime}$ and, for every $a \in A$ and $a^{\prime} \in A^{\prime}, a \sim^{\prime} a^{\prime}$ iff $a^{\prime} \in A$ and $a \leadsto a^{\prime}$. The latter is strictly stronger than the mere inclusion $\leadsto \subseteq \sim^{\prime}$, and is indeed sufficient to deduce conservativity for the induced equational systems from the confluence of the super-ARS [Ter03. Exercice 1.3.21 (iii)]. But $\left(\Lambda, \rightarrow_{\Lambda}\right)$ is not a sub-ARS of $\left(\mathrm{R}\left\langle\Delta_{\mathrm{R}}\right\rangle, \Im\right)$, even when R is positive: for instance, if $\mathrm{R}=\mathbf{Q}^{+}$and $M \rightarrow_{\Lambda} M^{\prime} \neq M$, we have $\underline{M}=\frac{1}{2} \underline{M}+\frac{1}{2} \underline{M} \rightrightarrows \frac{1}{2} \underline{M}+\frac{1}{2} \underline{M^{\prime}} \notin \underline{\Lambda}$. So one must design another approach.

Given $\sigma \in \mathrm{R}\left\langle\Delta_{\mathrm{R}}\right\rangle$, one can consider the finite set of $\lambda$-terms $\Lambda(\sigma) \subset \Lambda$ obtained by keeping exactly one element in the support of each sum occurring in $\sigma$ (Vau09. Definition 3.18]. The second author tried to establish the conservativity of $\widetilde{\rightarrow}^{*}$ over $\rightarrow_{\Lambda}^{*}$ by iterating the following:
Claim 2.1 (Vau09, Lemma 3.20]). If $\sigma \rightrightarrows \sigma^{\prime}$ and $M^{\prime} \in \Lambda\left(\sigma^{\prime}\right)$ then there exists $M \in \Lambda(\sigma)$ such that $M \rightarrow_{\Lambda}^{*} \bar{M}^{\prime}$.

But the latter claim is wrong! Consider, for instance, $\sigma=(\lambda x \cdot(\underline{x}) \underline{x})(\underline{y}+\underline{z}) \widetilde{\rightarrow} \sigma^{\prime}=$ $(\underline{y}+\underline{z})(\underline{y}+\underline{z})$. We have $M^{\prime}=(y) z \in \Lambda\left(\sigma^{\prime}\right)$ but no term in $\Lambda\left(\sigma^{\prime}\right)=\{(\lambda x .(x) x) y,(\lambda x .(x) x) z\}$ $\beta$-reduces to $M^{\prime}$. Note that, in this counter-example, there is no $M \in \Lambda$ such that $\underline{M} \widetilde{\rightarrow}^{*} \sigma$ : somehow, we must exploit this additional hypothesis to establish a correct version of claim 2.1.

Reasoning on $\widetilde{\rightarrow}^{*}$ directly is difficult, due to its definition as a reflexive and transitive closure. The technique we propose involves the definition of a mixed-type relation $M \Vdash \sigma$ between a $\lambda$-term $M$ and a term $\sigma \in \mathrm{R}\left\langle\Delta_{\mathrm{R}}\right\rangle$ : intuitively, $M \Vdash \sigma$ when $\sigma$ is obtained by pasting together terms issued from various reductions of $M$, and we say $M \Vdash \sigma$ is a mashup of such reductions. In particular: $M \Vdash \underline{M^{\prime}}$ as soon as $M \rightarrow_{\Lambda}^{*} M^{\prime}$; and $M \Vdash \sigma+\tau$ as soon as $M \Vdash \sigma$ and $M \Vdash \tau$. We then show that $\stackrel{H}{ }$ is conservative over $\rightarrow_{\Lambda}^{*}$ (lemma 3.4 and that $M \Vdash \sigma$ as soon as $\underline{M} \xrightarrow{3}^{*} \sigma$ (lemmas 3.3 and 4.2 : this ensures the conservativity of $\rightarrow^{*}$ over $\rightarrow_{\Lambda}^{*}$ (theorem 4.3. Our whole approach thus rests on the careful definition of the mashup relation. Among other requirements, it must behave well w.r.t. the structure of terms: e.g., if $M \Vdash \sigma$ then $\lambda x . M \Vdash \lambda x . \sigma$.

## 3 Mashup of $\beta$-reductions

We define two relations $\vdash \subseteq \Lambda \times \Delta_{R}$ and $\Vdash \subseteq \Lambda \times R\left\langle\Delta_{R}\right\rangle$ by mutual induction, with the rules of fig. 1. If $\sigma \in \mathrm{R}\left\langle\Delta_{\mathrm{R}}\right\rangle$, we write $\operatorname{Supp}(\sigma) \subset \Delta_{\mathrm{R}}$ for its support set.

Lemma 3.1. We have $M \Vdash \sigma$ iff, for every $\sigma^{\prime} \in \operatorname{Supp}(\sigma), M \vdash \sigma^{\prime}$.
Proof. The forward implication is done by induction on the derivation of $M \Vdash \sigma$, noting that if $\sigma^{\prime} \in \operatorname{Supp}(a \tau+\rho)$ with $M \vdash \tau$ and $M \Vdash \rho$ then $\sigma^{\prime}=\tau$ or $\sigma^{\prime} \in \operatorname{Supp}(\rho)$. For the reverse implication, we can write $\sigma=\sum_{i=1}^{n} a_{i} . \sigma_{i}$ with $\sigma_{i} \in \operatorname{Supp}(\sigma)$ for $1 \leq i \leq n$, and obtain a derivation of $M \Vdash \sigma$ by induction on $n$.

$$
\begin{gathered}
\frac{M \vdash \sigma}{M \Vdash \sigma}(\mathrm{~s}) \\
\frac{M \rightarrow_{\Lambda}^{*} \lambda x . N \quad N \Vdash \tau}{M \Vdash \lambda x . \tau}\left(\lambda^{\prime}\right) \quad \frac{M \rightarrow_{\Lambda}^{*}(N) P \quad N \Vdash \tau \quad P \Vdash \rho}{M \Vdash(\tau) \rho}\left(\mathrm{a}^{\prime}\right) \quad \frac{M \Vdash \sigma \quad M \Vdash \tau}{M \Vdash a . \sigma+\tau}\left(+{ }^{\prime}\right)
\end{gathered}
$$

Figure 2: Admissible rules for the mashup relations

Lemma 3.2. The rules of fig. 2are admissible.
Proof. For (s), it is sufficient to observe that $\sigma=1 \sigma+\mathbf{0}$. For the other three rules, we reason on the support sets, using lemma 3.1 .

Lemma 3.3 (Reflexivity of $\vdash$ ). For every $M \in \Lambda, M \vdash \underline{M}$.
Proof. By a straightforward induction on $M$, using the reflexivity of $\rightarrow_{\Lambda}^{*}$ and rule (s).
Lemma 3.4 (Conservativity of $\Vdash$ ). If $M \Vdash \underline{M^{\prime}}$ then $M \rightarrow_{\Lambda}^{*} M^{\prime}$.
Proof. Note that $\underline{M^{\prime}} \in \Delta_{\mathrm{R}}$, hence $M \vdash \underline{M^{\prime}}$ by lemma 3.1. The proof is then by induction on $M^{\prime}$, inspecting the last rule of the derivation of $M \vdash \underline{M^{\prime}}:$
(v) If $M \rightarrow_{\Lambda}^{*} x$ and $\underline{M}^{\prime}=\underline{x}$ then we conclude directly since $M^{\prime}=x$.
( $\lambda$ ) If $M \rightarrow_{\Lambda}^{*} \lambda x . N$ and $N \vdash \tau$ with $\underline{M^{\prime}}=\lambda x . \tau$, then $M^{\prime}=\lambda x . N^{\prime}$ with $\tau=\underline{N^{\prime}}$. By induction hypothesis, $N \rightarrow_{\Lambda}^{*} N^{\prime}$, hence $M \rightarrow_{\Lambda}^{*} M^{\prime}$.
(a) If $M \rightarrow_{\Lambda}^{*}(N) P, N \vdash \tau$ and $P \Vdash \rho$ with $\underline{M^{\prime}}=(\tau) \rho$, then $M^{\prime}=\left(N^{\prime}\right) P^{\prime}$ with $\tau=\underline{N^{\prime}}$ and $\rho=\underline{P^{\prime}}$. In particular $\rho \in \Delta_{\mathrm{R}}$, hence $P \vdash \rho$ by lemma 3.1. By induction hypothesis, $N \rightarrow_{\Lambda}^{*} N^{\prime}$ and $P \rightarrow_{\Lambda}^{*} P^{\prime}$, hence $M \rightarrow_{\Lambda}^{*} M^{\prime}$.

Lemma 3.5 (Compatibility with $\rightarrow_{\Lambda}$ ). If $M \rightarrow_{\Lambda}^{*} M^{\prime} \vdash \sigma$ then $M \vdash \sigma$. Similarly, if $M \rightarrow_{\Lambda}^{*}$ $M^{\prime} \Vdash \sigma$ then $M \Vdash \sigma$.

Proof. For the first implication, it is sufficient to inspect the last rule of the derivation $M^{\prime} \vdash \sigma$, and use the transitivity of $\rightarrow_{\Lambda}^{*}$. The second implication follows directly by induction on the derivation of $M^{\prime} \Vdash \sigma$.

## 4 Conservativity of algebraic reduction

Lemma 4.1 (Substitution lemma). If $M \Vdash \sigma$ and $P \Vdash \rho$ then $M[P / x] \Vdash \sigma[\rho / x]$.
Proof. We prove the result, together with the variant assuming $M \vdash \sigma$ instead of $M \Vdash \sigma$, by induction on the derivations of those judgements.
(v) If $M \rightarrow_{\Lambda}^{*} y$ and $\sigma=\underline{y}$ then:

- if $y=x$, then $M[P / x] \rightarrow_{\Lambda}^{*} x[P / x]=P \Vdash \rho$ and we obtain $M[P / x] \Vdash \rho=\sigma[\rho / x]$ by lemma 3.5.
- otherwise, $M[P / x] \rightarrow_{\Lambda}^{*} y[P / x]=y$, hence $M[P / x] \Vdash \underline{y}=\sigma[\rho / x]$ by $(\mathrm{v})$.
( $\lambda$ ) If $M \rightarrow_{\Lambda}^{*} \lambda y . N$ and $N \vdash \tau$ with $\sigma=\lambda y . \tau$ (choosing $y \neq x$ and $y$ not free in $P$ nor in $\rho$ ), then $M[P / x] \rightarrow_{\Lambda}^{*} \lambda y . N[P / x]$ and, by induction hypothesis $N[P / x] \Vdash \tau[\rho / x]$ : we obtain $M[P / x] \Vdash \lambda y . \tau[\rho / x]=\sigma[\rho / x]$ by $\left(\lambda^{\prime}\right)$.
(a) If $M \rightarrow_{\Lambda}^{*}\left(N_{1}\right) N_{2}, N_{1} \vdash \tau_{1}$ and $N_{2} \Vdash \tau_{2}$, with $\sigma=\left(\tau_{1}\right) \tau_{2}$, then we have $M[P / x] \rightarrow_{\Lambda}^{*}$ $\left(N_{1}[P / x]\right) N_{2}[P / x]$ and, by induction hypothesis, $N_{1}[P / x] \Vdash \tau_{1}[\rho / x]$ and $N_{2}[P / x] \Vdash$ $\tau_{2}[\rho / x]$ : we obtain $M[P / x] \Vdash\left(\tau_{1}[\rho / x]\right) \tau_{2}[\rho / x]=\sigma[P / x]$ by $\left(a^{\prime}\right)$.
(0) If $\sigma=\mathbf{0}$ then $\sigma[\rho / x]=\mathbf{0}$ and we conclude directly, by ( $\mathbf{0}$ ).
$(+)$ If $\sigma=a . \tau_{1}+\tau_{2}$ with $M \vdash \tau_{1}$ and $M \Vdash \tau_{2}$, then, by induction hypothesis, $M[P / x] \Vdash \tau_{1}[\rho / x]$ and $M[P / x] \Vdash \tau_{2}[\rho / x]$, hence $M[P / x] \Vdash a . \tau_{1}[\rho / x]+\tau_{2}[\rho / x]=\sigma[\rho / x]$ by $\left(a^{\prime}\right)$.
Note that, by positivity, if $\sigma=a . \tau+\rho$ with $\tau \in \Delta_{\mathrm{R}}$ and $a \neq 0$, then $\tau \in \operatorname{Supp}(\sigma) \supseteq \operatorname{Supp}(\rho)$.
Lemma 4.2 (Compatibility with $\widetilde{\rightarrow}$ ). Let $M \in \Lambda$ and $\sigma^{\prime} \in \mathrm{R}\left\langle\Delta_{R}\right\rangle$. For every $\sigma \in \Delta_{R}$ such that $M \vdash \sigma \rightarrow \sigma^{\prime}$ (resp. every $\sigma \in \mathrm{R}\left\langle\Delta_{\mathrm{R}}\right\rangle$ such that $M \Vdash \sigma \Im \sigma^{\prime}$ ), we have $M \Vdash \sigma^{\prime}$.
Proof. The proof is by induction on the definition of the reduction $\sigma \rightarrow \sigma^{\prime}$ or $\sigma \rightrightarrows \sigma^{\prime}$.
- If $\sigma=(\lambda x . \tau) \rho \in \Delta_{\mathrm{R}}$ and $\sigma^{\prime}=\tau[\rho / x]$, then the derivation of $M \vdash \sigma$ must be of the form

$$
\frac{M \rightarrow_{\Lambda}^{*}(N) P \quad \frac{N \rightarrow_{\Lambda}^{*} \lambda x . N^{\prime} \quad N^{\prime} \vdash \tau}{N \vdash \lambda x . \tau}(\lambda) \quad P \Vdash \rho}{M \vdash(\lambda x . \tau) \rho}(\mathrm{a}) .
$$

By lemma 4.1, we have $N^{\prime}[P / x] \Vdash \sigma^{\prime}$. Moreover, $M \rightarrow_{\Lambda}^{*}(N) P \rightarrow_{\Lambda}^{*}\left(\lambda x . N^{\prime}\right) P \rightarrow_{\Lambda}$ $N^{\prime}[P / x]$ and we obtain $M \Vdash \sigma^{\prime}$ by lemma 3.5 .

- If $\sigma=\lambda x . \tau$ and $\sigma^{\prime}=\lambda x . \tau^{\prime}$ with $\tau \rightarrow \tau^{\prime}$, then the derivation of $M \vdash \sigma$ must be of the form

$$
\frac{M \rightarrow_{\Lambda}^{*} \lambda x . N \quad N \vdash \tau}{M \vdash \lambda x . \tau}(\lambda)
$$

We obtain $N \Vdash \tau^{\prime}$ by induction hypothesis, and we conclude by ( $\lambda^{\prime}$ ).

- If $\sigma=(\tau) \rho$ and $\sigma^{\prime}=\left(\tau^{\prime}\right) \rho^{\prime}$ with either $\tau \rightarrow \tau^{\prime}$ and $\rho=\rho^{\prime}$, or $\tau=\tau^{\prime}$ and $\rho \widetilde{\rightarrow} \rho^{\prime}$, then the derivation of $M \vdash \sigma$ must be of the form

$$
\frac{M \rightarrow_{\Lambda}^{*}(N) P \quad N \vdash \tau \quad P \Vdash \rho}{M \vdash(\tau) \rho}(\mathrm{a})
$$

We obtain $N \Vdash \tau^{\prime}$ and $P \Vdash \rho^{\prime}$ by induction hypothesis, and we conclude by (a').

- If $\sigma=a . \tau+\rho$ and $\sigma^{\prime}=a . \tau^{\prime}+\rho$ with $\tau \rightarrow \tau^{\prime}$ and $a \neq 0$, then we have already observed that $\tau \in \operatorname{Supp}(\sigma)$ and $\operatorname{Supp}(\rho) \subseteq \operatorname{Supp}(\sigma)$. Since $M \Vdash \sigma$, we obtain $M \vdash \tau$ and $M \Vdash \rho$ by lemma 3.1. The induction hypothesis gives $M \Vdash \tau^{\prime}$, hence $M \Vdash a \cdot \tau^{\prime}+\rho=\sigma^{\prime}$ by $(+')$.
Theorem 4.3 (Conservativity of $\widetilde{\rightarrow}^{*}$ ). If $\underline{M} \widetilde{\rightarrow}^{*} \underline{N}$ then $M \rightarrow_{\Lambda}^{*} N$.
Proof. Assume $\underline{M} \widetilde{\rightarrow}^{*} \underline{N}$. By lemma 3.3 and (s), we have $M \Vdash \underline{M}$. By iterating lemma 4.2 , we deduce $M \Vdash \underline{N}$. We conclude by lemma 3.4.
Corollary 4.4 (Conservativity of $\leftrightarrow)$. If R is positive then $\underline{M} \leftrightarrow \underline{N}$ iff $M \leftrightarrow_{\Lambda} N$.
Proof. Assuming $\underline{M} \leftrightarrow \underline{N}$, the confluence of $\rightrightarrows$ ensures that there exist $\sigma \in \mathrm{R}\left\langle\Delta_{\mathrm{R}}\right\rangle$ and $k \in \mathbf{N}$, such that $\underline{M} \widetilde{\rightarrow}^{k} \sigma$ and $\underline{N} \widetilde{\rightarrow}^{*} \sigma$. It follows [Vau09. Lemma 3.23] that $\sigma \widetilde{\rightarrow}^{*} \underline{M} \downarrow^{k}$ where $\tau \downarrow$ is the term obtained by reducing all the redexes of $\tau$ simultaneously. Observing that $\underline{M} \downarrow=\underline{M} \downarrow$, we obtain $\underline{N} \widetilde{\rightarrow}^{*} M \downarrow^{k}$ hence $N \rightarrow_{\Lambda}^{*} M \downarrow^{k}$ by theorem 4.3. which concludes the proof.


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# Nijn/ONijn: A New Certification Engine for Higher-Order Termination* 

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## 1 Introduction

In this short paper, we limn a new combination Nijn/ONijn for the certification of higher-order rewriting termination proofs. A complete version of this work has been accepted for publication at ITP 2023 [8]. We follow the following system design in Nijn/ONijn: Nijn [7] is the certifier, a Coq library providing a formalization of the underlying higher-order rewriting theory and ONijn [6] is a proof script generator, an application that when given a minimal description of a termination proof, i.e., proof trace, outputs a Coq proof script. The proof script is a fully formal description of the syntax signature used by the TRS and the specification of each rule in the system together with the formal steps needed to express its termination. The proof script then utilizes results from Nijn for checking the correctness of the traced proof. Examples of this system design are the combinations Cochinelle/CiME3 [2] and CoLoR/Rainbow [1].

The schematic below depicts the basic steps for producing proof certificates using Nijn/ONijn.


Figure 1: Nijn/ONijn schematics

A termination prover in this schematic is an abstract entity responsible for producing proof traces. It can be either a human, proving termination manually, or a termination tool like Wanda 4], which uses programmed techniques and automated reasoning tools such as SAT/SMT solvers. Whenever a prover outputs a proof trace, we can use ONijn to process it into a formal proof script in Coq. At this moment, we have formalized the polynomial interpretation method.

[^3]Notice that producing the certificates for only this proof method is an inherently incomplete task, since it would require a method to solve inequalities over arbitrary polynomials, which is undecidable in general.

While Nijn is the certified core part of our tool since it is checked by Coq, the proof script generation implemented in OCaml ( ONijn ) is not currently certified and must be trusted. For this reason, we deliberately keep ONijn as simple (small) as possible. The main task delegated to ONijn is that of parsing the proof trace given by the termination prover to a Coq proof script and perform sanitazation on the prover's input, so that syntax errors are avoided in the proof script. This approach does not pose significant drawbacks in our experience.

## 2 Encoding TRSs in Nijn

Let us encode $\mathcal{R}_{\text {map }}$ in Coq using Nijn. This will be useful to demonstrate our choices in the formalization and show how to express rewriting systems directly in Coq. The file containing the full enconding can be found at Map.v. A simple example of a higher-order system is that of $\mathcal{R}_{\text {map }}$. It represents the higher-order function that applies a function to each element of a list. Recall that $\mathcal{R}_{\text {map }}$ is composed of two rules: map $F$ nil $\rightarrow$ nil and map $F(\operatorname{cons} x x s) \rightarrow \operatorname{cons}(F x)(\operatorname{map} F x s)$. These rules are under a typing context where $F$ : nat $\Rightarrow$ nat, $x:$ nat, and $x s:$ list. We start by encoding base types.

```
Inductive base_types := TBtype| TList.
Definition Btype : ty base_types := Base TBtype.
Definition List : ty base_types := Base TList.
```

The abbreviations Btype and List is to smoothen the usage of the base types. There are three function symbols in this system:

Inductive fun_symbols $:=$ TNil $\mid$ TCons $\mid$ TMap.
The arity function map_ar maps each function symbol in fun_symbols to its type.

```
Definition map_ar f : ty base_types
    := match f with
        |Nil # List
        TCons }=>\mathrm{ Btype }\longrightarrow\mathrm{ List }\longrightarrow\mathrm{ List
        \| ~ T M a p ~ = ~ ( B t y p e ~ \longrightarrow ~ B t y p e ) ~ \longrightarrow ~ L i s t ~ \longrightarrow ~ L i s t ~
        end.
```

So, TNil is a list and given an inhabitant of Btype and List, the function symbol TCons gives a List. Again we introduce some abbreviations to simplify the usage of the function symbols.

```
Definition Nil {C} : tm map_ar C _ := BaseTm TNil.
Definition Cons {C} x xs : tm map_ar C _ := BaseTm TCons · x · xs.
Definition Map {C} f xs : tm map_ar C _ := BaseTm TMap | f | xs.
```

The first rule, map $F$ nil $\rightarrow$ nil, is encoded as the following Coq construct:

```
Program Definition map_nil :=
    make_rewrite
        (_ ,, \bullet) _
        (let f := TmVar Vz in Map · f | Nil)
        Nil.
```

Notice that we only defined the pattern of the first two arguments of make_rewrite, leaving the types in the context (,$~ \bullet \bullet)$ and the type of the rule unspecified. Coq can fill in these holes
automatically, as long as we provide a context pattern of the correct length. In this particular rewrite rule, there is only one free variable. As such, the variable TmVar Vz refers to the only variable in the context. In addition, we use iterated let-statements to imitate variable names. For every position in the context, we introduce a variable in Coq, which we use in the leftand right-hand sides of the rule. This makes the rules more human-readable. Indeed, the lhs $\operatorname{map} F$ nil of this rule is represented as Map •f.Nil in code. The second rule for map is encoded following the same ideas.

```
Program Definition map_cons:=
    make_rewrite
```



```
        (let \(\mathrm{f}:=\operatorname{TmVar} \operatorname{Vz}\) in let \(\mathrm{x}:=\operatorname{TmVar}(\mathrm{Vs} \mathrm{Vz})\) in let \(\mathrm{xs}:=\operatorname{TmVar}(\mathrm{Vs}(\mathrm{Vs} \mathrm{Vz}))\) in
        Map \(\cdot \mathrm{f} \cdot(\) Cons \(\cdot \mathrm{x} \cdot \mathrm{xs})\) )
        (let \(\mathrm{f}:=\operatorname{TmVar} \operatorname{Vz}\) in let \(\mathrm{x}:=\operatorname{TmVar}(\mathrm{Vs} \operatorname{Vz})\) in let \(\mathrm{xs}:=\operatorname{TmVar}(\mathrm{Vs}(\mathrm{Vs} V z)\) ) in
        Cons • (f • x) • (Map • f x x\()\) ).
```


## 3 Practical Aspects of Nijn/ONijn Certification

In this section, we discuss the practical aspects of our verification framework. In principle one can manually encode rewrite systems as Coq files and use the formalization we provide to verify their own termination proofs. However, this is cumbersome to do so. Indeed, in the last section we used abbreviations to make the formal description of $\mathcal{R}_{\text {map }}$ more readable. A rewrite system with many more rules would be difficult to encode manually. Additionally, to formally establish termination we also need to encode proofs. The full formal encoding of $\mathcal{R}_{\text {map }}$ and its termination proof is found in the file Map.v.

### 3.1 Proof traces for polynomial interpretation

This difficulty of manual encoding motivates the usage of proof traces. A proof trace is a human-friendly encoding of a TRS and the essential information needed to reconstruct the termination proof as a Coq script. Let us again consider $\mathcal{R}_{\text {map }}$ as an example. The proof trace for this system starts with YES to signal that we have a termination proof for it. Then we have a list encoding the signature and the rules of the system.

```
YES
Signature: [
    cons : a -> list -> list ;
    map : list -> (a -> a) -> list ;
    nil : list
]
Rules: [
    map nil F => nil ;
    map (cons X Y) G => cons (G X) (map Y G)
]
```

Notice that the free variables in the rules do not need to be declared nor their typing information provided. Coq can infer this information automatically. The last section of the proof trace describes the interpretation of each function symbol in the signature.

```
Interpretation: [
    J(cons) = Lam[y0;y1].3 + 2*y1;
    J(map) = Lam[y0;G1].3*y0 + 3*y0 * G1(y0);
    J(nil) = 3
]
```

We can fully reconstruct a formal proof of termination for $\mathcal{R}_{\text {map }}$, which uses the theory formalized in Nijn, with the information provided in the proof trace above. The full description of proof traces can be found in [6], the API for ONijn. Proof traces are not Coq files. So we need to further compile them into a proper Coq script. The schematics in fig. 1 describe the steps necessary for it. We use ONijn to compile proof traces to Coq script. It is invoked as follows:

```
onijn path/to/proof/trace.onijn -o path/to/proof/script.v
```

Here, the first argument is the file path to a proof trace file and the -o option requires the file path to the resulting Coq script. The resulting Coq script can be verified by Nijn as follows:

```
coqc path/to/proof/script.v
```

Instructions on how to locally install ONijn/Nijn can be found at 6].

### 3.2 Verifying Wanda's Polynomial Interpretations

It is worth noticing that the termination prover is abstract in our certification framework. This means that we are not bound to a specific termination tool. So we can verify any termination tool that implements the interpretation method described here and can output proof traces in ONijn format.

Since Wanda [4] is a termination tool that implements the interpretation method in 3], it is our first candidate for verification. We added to Wanda the runtime argument --formal so it can output proof traces in ONijn format. In 4] one can find details on how to invoke Wanda. For instance, we illustrate below how to run Wanda on the map AFS.
./wanda.exe -d rem --formal Mixed_HO_10_map.afs
The setting -d rem sets Wanda to disable rule removal. The option --formal sets Wanda to only use polynomial interpretations and output proofs to ONijn proof traces. Running Wanda with these options gives us the proof trace we used for $\mathcal{R}_{\text {map }}$ above. The latest version of Wanda, which includes this parameter, is found at 5].

The table below describes our experimental evaluation on verifying Wanda's output with the settings above. The benchmark set consists of those 46 TRSs that Wanda outputs YES while using only polynomial interpretations and no rule removal. The time limit for certification of each system is set to 60 seconds.

The experiment was run in a machine with M1 Pro 2021 processor with 16GB of RAM. Memory usage of Nijn during certification ranges from 400 MB to 750 MB . We provide the experimental benchmarks at https://github.com/deividrvale/nijn-coq-script-generation.

|  | Wanda |  | Nijn/ONijn |  |  |  |
| :--- | :---: | :---: | :---: | :---: | :---: | :---: |
| Technique | \# YES | Pct. | Avg. Time | \# Certified | Perc. | Avg. Time |
| Poly, no rule removal | 46 | $23 \%$ | 0.07 s | 46 | $100 \%$ | 4.06 s |

Table 1: Experimental Results
Hence, we can certify all TRSs proven SN by Wanda using only polynomial interpretations.

## 4 Conclusion and Future Plans

In this formalization effort, we were successful in certifying higher-order polynomial interpretations. This line of work is far from finished, however. The initial setup of Nijn/ONijn presented here bootstraps the foundation of a full-fledged certification engine for more complex higher-order termination proof techniques. For instance, incorporating the so-called higher-order dependency pair framework is our next immediate future work plan. This will allow us to significantly improve the number of systems we can certify.

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[^0]:    ${ }^{1} \mathrm{t} @ \mathrm{~s}$ is the abbreviation of $\operatorname{app}(\mathrm{t}, \mathrm{s})$.

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